An Improved Algorithm for Optimal Solution of Unbalanced Transportation Problems

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Abstract

Unbalanced transportation problems are particular kind of transportation problems, but an optimal solution is hard to find for unbalanced transportation problems. Still there is a need for minimizing the transportation cost. Unbalanced–TP deals with two different cases, (i) Excess of accessibility $\sum_i A_i > \sum_j B_j$, (ii) Deficiency in accessibility $\sum_i A_i < \sum_j B_j$, here in this paper both the cases for getting better optimal solution are discussed. Proposed algorithm is based on dummy rows and dummy columns, by taking the absolute differences (penalty) of Initial & Last cost cells of each row/column in transportation cost-matrix, where the objective function is to find an optimal solution. This method is easy to understand and apply than the other existing methods using Initial Basic Feasible Solution–IBFS. Therefore, the proposed method is very helpful to get optimal solution for unbalanced transportation problems.

Keywords:Initial Basic Feasible Solution–IBFS, Unbalanced Transportation Problems, Dummy Rows & Dummy Columns, Optimal Solution.

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1. INTRODUCTION

In Operation Research–OR, Transportation Problem–TP is specific kind of sub-division of linear programming– LP problems. It is commonly significant in the scheme of decision making [1]. Wherein purpose is to lessen the cost of transportation for businesses with number of destination, while sustaining supply limit and demand prerequisite [2]. To get this aim of cost, we have the quantity and locality of already accessible supplies and the amount demanded on top of the participation united accompanied by each 'sending'. The term 'Transportation Model' is some time deceive because it can be used for plant location, machine assignment, product mix problems and many more as well. Whereas the model is really not limited to transportation/distribution only [5]. Linear programming is a mathematical technique which is widely used in fields of social sciences and business domain. For example: Transportation Problems, Allocation Problems, Diet Problems, Agriculture Problems, Network Flow Problems, Marketing Engineering and several others. L.F. Hitchcock (1941) initially established basic transportation problems. The motive of transportation problem controls optimal distribution arrangements between origins/sources and destinations, which are basically accumulated at many origins to diverse destinations in such a way that the cost of total transportation is minimized [4, 7, 10]. There are two forms of transportation problems.

1.1 Balanced and Unbalanced Transportation Problem

A transportation problem is known as balanced when the summation of all supply bases are equal to the summation of all demand purposes, i.e. $\sum_{i=1}^{m} A_i = \sum_{j=1}^{n} B_j$ otherwise it is known as unbalanced transportation problem, i.e. $\sum_{i=1}^{m} A_i > \sum_{j=1}^{n} B_j$ or $\sum_{i=1}^{m} A_i < \sum_{j=1}^{n} B_j$, to satisfy both the conditions of unbalanced transportation problems, they are presented with a dummy row or dummy column. If the sum of sources is greater than the sum of requirements, then the dummy destinations are presented with requirements, to solve the difference between sum of sources and sum of requirements cost, the dummy rows and dummy columns are set equal to zero transportation cost [6, 8].

In previous, studies many researchers have discussed different methods to solve the transportation problems of Initial Basic Feasible Solution–IBFS and optimal methods. The most advantageous and useful ways for initial basic feasible solution are North-West Corner Method–NWCM, Least-Cost Method–LCM, Vogel's Approximation Method–VAM and several other. Other methods like Modified Distribution–MODI Method and Stepping Stone Method–SSM are used for an optimal solution of transportation problems. Some important related works in last few years has dealt with. Z.A.M.S. Juman & N.G.S.A. Nawarathne [8] Considered only row penalties using Juman and Hoque (2015)'s Method–JHM, for solving the I.B.F.S of conservative transportation problem. A. Rashid [9] He proposed a different approach which can help the decision makers in handling unbalanced transportation assignment problems to minimize the costs of total transportation and maximize the total profits. A. Sridhar & N. Girmay, et al [11, 12] suggests a Heuristic Approach to get improved results of

unbalanced transportation problems, and improved the existing VAM. This study has minimized the transportation costs in an easy and effective manner. A. Quddoos, et al [13] has proposed method named ASM-Method to find optimal solution of transportation problems, directly. This method requires easy arithmetical and logical calculation with less time period, and results are comparable to existing MODI-Method and Stepping Stone Method. Rajendra B. Patel [14] the presented method is a little modification of ASM-Method. M. Palanivel, et al [15] analyzed an innovative procedure for solving problems of transportation by using Harmonic Mean Approach. Ravi Kumar R, et al [16] they proposed a new technique named Direct Sum Method using VAM, to discover the I.B.F.S of transportation problems. A. Seethalakshmy & N. Srinivasan [17] proposed a different technique to resolve of unbalanced transportation assignment problems, based on finding the position of '1' by using systematic procedure. This article gives same result as that of the Hungarian Method with less consumption of time. M. A. Metlo, et al [18] Modified North-West Corner Method-MNWCM is developed to discover I.B.F.S based on NWCM. The main objective of this study is to reduce the size of iterations and is used to achieve an optimal solution with minimum time estimation, also the results are compared with existing NWCM.

This paper is a motivation for finding better optimal solution for unbalanced transportation problems. This leads to a different approach than the previous methods to minimize the total cost and to maximize the profit in transporting commodities from sources to destinations. The proposed method is introduced below:

2. METHODOLOGY:

2.1 Mathematical Formulation of Unbalanced Transportation Model:

Mathematically, the general transportation model is given as follows:

Minimize: (Total transportation cost) $\mathbf{Z} = \sum_{i=1}^{m} \sum_{j=1}^{n} C_{ij} U_{ij}$ (1)

Subject to:	(Supply from sources)	$\sum_{i=1}^{m} U_{ij} \leq A_i;$	i = 1, 2,,m	(2)
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- (3)
- Where (4)
- $\sum_{i=1}^{m} A_i \neq \sum_{j=1}^{n} B_j$ (For an unbalanced transportation problem) (5)

The unbalanced transportation problems are of two cases (i) $\sum_{i} A_{i} > \sum_{i} B_{i}$ and (ii) $\sum_{i} A_{i} < \sum_{i} B_{i}$. There are two feasible cases:

(Excess accessibility)
$$\sum_{i=1}^{m} A_i > \sum_{j=1}^{n} B_j$$
 (6)

(A dummy purpose)
$$D_{n+1}$$
 (7)
 $B_{n+1} = \sum_{i=1}^{m} A_i - \sum_{i=1}^{n} B_i$: $U_{i,n+1} = 0$: $i = 1, 2, ..., m$ (8)

$$\sum_{i=1}^{m} A_i < \sum_{j=1}^{n} B_j$$
(0)
(Deficiency in accessibility)
$$\sum_{i=1}^{m} A_i < \sum_{j=1}^{n} B_j$$
(1)

(A dummy basis)
$$S_{m+1}$$
 (10)
 $A_{m+1} = \sum_{j=1}^{n} B_j - \sum_{i=1}^{m} A_i;$ $U_{m+1, j} = 0;$ $j = 1, 2, ..., n$ (11)

Necessary condition for presence of a feasible solution of unbalanced transportation problems are $\sum_{i=1}^{m} A_i = \sum_{j=1}^{n+1} B_j$ or $\sum_{i=1}^{m+1} A_i = \sum_{j=1}^{n} B_j$. i.e., the summation of total supply must equal to the summation of total demand [3].

2.1.1 PROPOSED ALGORITHM:

i.

ii.

Step#01:- Case (i) whenever $\sum_{i} A_{i} > \sum_{i} B_{i}$, add $C_{ij+1} = 0 \forall$ dummy column based on the demand (B_{j+1}) , and calculate the absolute differences (penalty) between Initial & Last cost cells of each column in transportation cost-matrix, (ignoring differences (penalty) of Initial & Last cost cells of dummy column and all rows), then identify maximum penalty (P_i) for allocation.

Case (ii) whenever $\sum_{i} A_{i} < \sum_{i} B_{i}$, add $C_{ii+1} = 0 \forall$ dummy row based on the supply (A_{i+1}), and calculate the absolute differences (penalty) between Initial & Last cost cells of each row in transportation cost-matrix, (ignoring differences (penalty) of Initial & Last cost cells of dummy row and all columns), then identify maximum penalty (P_i) for allocation.

Mathematically,

 $C_{ij+1} = 0 \forall$ dummy rows & dummy columns.

 $\mathbf{P}_i = |\mathbf{C}_{1n} - \mathbf{C}_{mn}| \forall$ rows penalty & $\mathbf{P}_j = |\mathbf{C}_{m1} - \mathbf{C}_{mn}| \forall$ columns penalty.

Step#02:- Choose the smallest cost cell C_{ii} in row/column and allocate with selected maximum penalty (P_i/P_i).

Step#03:- "In case of ties", If two or more of the smallest cost cells C_{ij} in row/column are same then select the top entry of them to allocate. If two or more of maximum penalty (P_i/P_i) are same then select the smallest cost cell C_{ii} in row/column.

Step#04:- Repeat steps (1 to 3) for remaining transportation cost-matrix, continue this procedure until all the supply (A_i) and demand (B_i) are become zero.

Note: The dummy row/column should be allocated in last.

Step#05:- Finally, calculate minimizing the total cost of transportation. i.e., **Tcost**, $\{Z = \sum_{i=1}^{m} \sum_{j=1}^{n} C_{ij}U_{ij}\}$.

3. NUMERICAL EXAMPLES

Consider the following different – sizes of both the cases of unbalanced transportation problems, selected from literature. We solve them using proposed algorithm and compare these results with the solution of NWCM, LCM & MODI–Method.

3.1 Example#1:- The Unbalanced-TF	of case (i) Excess of ac	cessibility $\sum_{i} A_{i} > \sum_{i} B_{i}$.
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•				<i>i</i> <u> </u>	
	Sources\Destinations	D_1	D_2	D_3	Supply (A _i)
	S_1	3	4	6	100
	S_2	7	3	8	80
	S ₃	6	4	5	90
	S ₄	7	5	2	120
	Demand (B _i)	110	110	60	∑ 280\390

Table: 3.1.1

Sources\Destinations	D ₁	D ₂	D3	Dummy column	Supply (A _i)
S ₁	3	4	6	0	100
S ₂	7	3	8	0	80
S ₃	6	4	5	0	90
S ₄	7	5	2	0	120
Demand (B _j)	110	110	60	110	∑ 390\390

Table: 3.1.2

Sources\Destinations	D ₁	D ₂	D ₃	Dummy column	Supply (A _i)
S ₁	3	4	6	0	100
S ₂	7	3	8	0	80
S ₃	6	4	5	0	90
S ₄	7	5	2	0	120
			60		60
Demand (B _j)	110	110	60	110	∑ 330\330
			0		
Column penalty (P _j)	(4)	(1)	(4)		

Table: 3.1.3

D ₁	D ₂	Dummy	Supply (A _i)
		column	
3	4	0	100
100			0
7	3	0	80
6	4	0	90
7	5	0	60
110	110	110	∑ 230\230
10			
(4)	(1)		
	3 100 7 6 7 110 10	3 4 100 100 7 3 6 4 7 5 110 110 10 10	column 3 4 0 100 7 3 0 6 4 0 7 7 5 0 110 100 110 110 110

Table: 3.1.4

Sources\Destinations	D1	D ₂	Dummy	Supply (A _i)			
			column				
S_2	7	3	0	80			
		80		0			
S ₃	6	4	0	90			
S_4	7	5	0	60			
Demand (B _i)	10	110	110	∑ 150\150			
30							
Column penalty (P _i)	(0)	(2)					
	Tal	ole: 3.1.5					

Sources\Destinations	D ₁	D ₂	Dummy column	Supply (Ai)
	-		colullil	
S_3	6	4	0	90
		30		60
S ₄	7	5	0	60
Demand (B _i)	10	30	110	<u>Σ</u> 120\120
· •/		0		_
Column penalty (P _j)	(1)	(1)		

Table: 3.1.6

Sources\Destinations	D ₁	Dummy column	Supply (A _i)
S_3	6	0	60 50
	10		50
S_4	7	0	60
Demand (B _j)	10	110	∑ 110\110
	0		
Column penalty (P _j)	(1)		

Table: 3.1.7

Sources\Destinations	Dummy	Supply (A _i)			
	column				
S ₃	0	50			
	50	0			
S ₄	0	60			
	60	0			
Demand (B _i)	110	$\sum 0 \setminus 0$			
	60				
	0				
Table: 3.1.8					

$U_{43} = 60, U_{11} = 100, U_{22} = 80, U_{32} = 30, U_{31} = 10, U_{34} = 50, \& U_{44} = 60.$

 $T \cos t, Z = (2*60) + (3*100) + (3*80) + (4*30) + (6*10) + (0*50) + (0*60) = 840/-$

Optimality Test

Formulate an optimality test by MODI–Method, to find whether the obtained feasible solution is optimal or not. Here, the number of allocations is equal to (m + n - 1) = 4 + 4 - 1 = 7, hence optimality test can be achieved. Find X's and Y's values using the formula $X_i + Y_j = C_{ij} \forall$ allocated cells, and set $X_1 = 0$. Then, find $d_{ij} = (X_i + Y_j) - C_{ij} \le 0 \forall$ unallocated cells.

Hence all $d_{ij} \le 0$, the solution given below is optimal.

Sources\Destinations	D1	D ₂	D ₃	Dummy	Supply (A _i)	Values
				column		(X_i)
S_1	<mark>3</mark>	4 1	6 -1	0 -3	100	$X_1 = 0$
	100	-3	-7	-3		
S_2	7 5	<mark>3</mark>	8 1	0 -1	80	$X_2 = 2$
	-2	<mark>80</mark>	-7	-1		
S ₃	<mark>6</mark>	<mark>4</mark>	5 2	0	90	$X_3 = 3$
	10	30	-3	50		
S ₄	7 6	5 4	2	0	120	$X_4 = 3$
	-1	-1	<u>60</u>	60		
Demand (B _j)	110	110	60	110	∑ 390\390	
Values (Y _j)	$Y_1 = 3$	$Y_2 = 1$	$Y_3 = -1$	$Y_4 = -3$		
· · ·	•	Table	: 3.1.9	•	·	•

3.2 Example#2:- The Unbalanced–TP of case (ii) Deficiency in accessibility $\sum_{i} A_{i} < \sum_{i} B_{i}$.

		2		2 - 1	, ,	
Sources\Destinations	D_1	D ₂	D ₃	D_4	Supply (A _i)	
S_1	10	15	12	12	200	
S_2	8	10	11	9	150	
S ₃	11	12	13	10	120	
Demand (B _i)	140	120	80	220	∑ 560\470	
Table: 3.2.1						

Sources\Destinations	D1	D ₂	D ₃	D4	Supply (A _i)
S ₁	10	15	12	12	200
S ₂	8	10	11	9	150
S ₃	11	12	13	10	120
Dummy row	0	0	0	0	90
Demand (B _j)	140	120	80	220	∑ 560\560

Table: 3.2.2

Sources\Destinations	D1	D ₂	D ₃	D4	Supply (A _i)	Row penalty
						(P _i)
S ₁	10	15	12	12	200	(2)
	140				60	
S_2	8	10	11	9	150	(1)
S ₃	11	12	13	10	120	(1)
Dummy row	0	0	0	0	90	
Demand (B _i)	140	120	80	220	∑ 420\420	
	0				_	

Table: 3.2.3

Sources\Destinations	D2	D3	D ₄	Supply (A _i)	Row penalty
					(P _i)
S_1	15	12	12	60	(3)
		60		0	
S ₂	10	11	9	150	(1)
S ₃	12	13	10	120	(2)
Dummy row	0	0	0	90	
Demand (B _i)	120	80	220	∑ 360\360	
		20		_	

Table: 3.2.4

Sources\Destinations	D ₂	D ₃	D4	Supply (A _i)	Row penalty
					(P _i)
S ₂	10	11	9	150	(1)
S ₃	12	13	10	120	(2)
			120	0	
Dummy row	0	0	0	90	
Demand (B _i)	120	20	220	∑ 240\240	
-			100		

Table: 3.2.5

Sources\Destinations	D ₂	D ₃	D4	Supply (A _i)	Row penalty
					(\mathbf{P}_i)
S_2	10	11	9	150	(1)
			100	50	
Dummy row	0	0	0	90	
Demand (B _i)	120	20	100	<u>Σ</u> 140\140	
× 3/			0	_	

Table: 3.2.6

Sources\Destinations	D ₂	D ₃	Supply (A _i)	Row penalty (P _i)
S ₂	10 50	11	50 0	(1)
Dummy row	0	0	90	
Demand (B _j)	120 70	20	∑ 90\90	

Table: 3.2.7

Sources\Destinations	D ₂	D ₃	Supply (A _i)
Dummy row	0 70	0 20	90 0
Demand (B _j)	70 0	20 0	∑ 0\0

Table: 3.2.8

 $U_{11} = 140, U_{13} = 60, U_{34} = 120, U_{24} = 100, U_{22} = 50, U_{42} = 70, \& U_{43} = 20.$

Tcost, Z = (10*140) + (12*60) + (10*120) + (9*100) + (10*50) + (0*70) + (0*20) = 4,720/-Optimality test, the number of allocations is equal to (m + n - 1) = 4 + 4 - 1 = 7. Hence all $d_{ii} \le 0$ the solution given below is optimal.

Sources\Destinations	D_1	D ₂	D ₃	D ₄	Supply (A _i)	Values
						(X_i)
\mathbf{S}_1	<mark>10</mark>	15 12	<mark>12</mark>	12 11	200	$X_1 = 0$
	140	-3	<mark>60</mark>	-1		
S_2	8 8	<mark>10</mark>	11 10	<mark>9</mark>	150	$X_2 = -2$
	0	<mark>50</mark>	-1	100		
S ₃	11 9	12 11	13 11	<mark>10</mark>	120	$X_3 = -1$
	-2	-1	-2	120		
Dummy row	0 -2	0	0	0 -1	90	$X_4 = -12$
	-2	70	20	-1		
Demand (B _i)	140	120	80	220	∑ 560\560	
Values (Y _i)	$Y_1 = 10$	$Y_2 = 12$	$Y_3 = 12$	$Y_4 = 11$		
	•	Tabl	e: 3.2.9	-	-	÷

4. COMPARISON OF RESULTS TABLE & DISCUSSION:

Consider the **Table 4.1.1**, we have solved the different real life problems by the proposed method. The following examples of case (i) 1, 3, 5 and case (ii) 2, 4, 6 are solved and several others, selected from literature. Also tested the performance of proposed method in comparison to NWC–Method, LC–Method & MODI–Method, and it can

Numerical	Rows	Columns	NWC-	LC–	Proposed-	Optimal Solution-
Examples			Method	Method	Method	MODI Method
Ex:1 [Ref: 8]	4	4	1,010	990	840	840
Ex:2 [Ref: 3]	4	4	5,070	5,260	4,720	4,720
Ex:3 [Ref: 6]	4	6	19,700	12,100	11,500	11,500
Ex:4 [Ref: 9]	4	4	3,550	3,225	3,100	3,100
Ex:5 [Ref: 1]	2	4	31,875	20,875	17,875	17,875
Ex:6 [Ref: 4]	5	3	14,140	12,550	11,720	11,720
			Та	hla: 11		

be clearly seen that the proposed method is same as the optimal results.



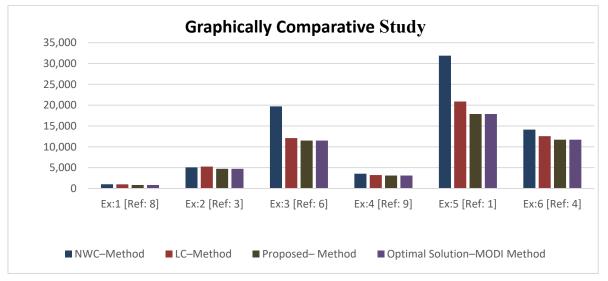


Fig: 1 Results are summarized in Table 4.1.1.

5. CONCLUSION

In this paper, we have promoted an improved algorithm for obtaining better optimal solution of unbalanced transportation problems. According to work computation, the proposed method is easy and less arithmetical calculation required to get optimal solution compared to existing MODI-Method. Also a comparison of proposed algorithm is made with NWC-Method, LC-Method and MODI-Method. Various numerical examples of different - sizes of both the cases are tested and critically observed that the proposed algorithm provide optimal solution directly.

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