# A Generalizing of the Fractional Sub-Equation Method to Solve Systems of the Space-Time Fractional Differential Equation 

Najati Jihad Abu Shawer<br>University of Jordan<br>najatiabushawer81@yahoo.com


#### Abstract

In the present paper, we construct the analytical solutions of some Space-Time nonlinear fractional order systems involving Jumarie's modified Riemann-Liouville derivative in mathematical physics : such that Space-Time fractional Whitham-Broer-Kaup equations, Space-Time fractional Breaking Soliton equations, Space-Time fractional Coupled Boussinesq- Burgers equations and Space-Time fractional Coupled Burgers Equations by using The fractional sub-equation method . this method is very powerful mathematical technique for finding exact solutions of nonlinear ordinary differential equations.


Key words: fractional sub-equation method, modified Riemann-Liouville derivative, Mittage-Leffler function.

## 1 Introduction :

Fractional differential equations are generalizations of classical differential equations of integer order. In recent years, nonlinear fractional differential equations (FDEs) have been attracted great interest. It is caused by both the development of the theory of fractional calculus itself and by the applications of such constructions in various sciences such as physics, engineering, and biology [1-7]. For better understanding the mechanisms of the complicated nonlinear physical phenomena as well as applying them in practical life, the solution of fractional differential equation is much involved [8-15].

Recently, Zhang and Zhang [16] introduced a new method called fractional sub-equation method to look for traveling wave solutions of nonlinear FDEs. The method is based on the homogeneous balance principle [17] and Jumarie's modified Riemann-Liouville derivative [18-19]. By using fractional sub-equation method, Zhang et al. successfully obtained traveling wave solutions of nonlinear time fractional biological population model and (4+ 1) dimensional space-time fractional Fokas equation. More recently, Guo et al. [20] and Lu [21] improved Zhang et al.'s work [16] and obtained exact solutions of some nonlinear FDEs.

In the present paper, the fractional sub-equation method will be employed on some systems involving Jumaries modified Riemann-Liouville derivative to find the exact solution for some Space-Time nonlinear fractional
systems, such that Space-Time fractional Whitham-Broer-Kaup equations, Space-Time fractional Breaking Soliton equations, Space-Time fractional Coupled Boussinesq- Burgers equations and Space-Time fractional Coupled Burgers Equations.The fractional sub-equation method is very powerful mathematical technique for finding exact solutions of nonlinear ordinary differential equations.

The rest of this paper is organized as follows. In Section 2, we will describe the Modified Riemann-Liouville derivative and give the main steps of method here. In Section 3, we give four applications of the proposed method. In Section 4, some conclusion are given.

## 2 Descriptions the Modified Riemann-Liouville Derivative and the Proposed

Method.

The Jumarie's Modified Riemann-Liouville Derivative of order $\alpha$ is defined by the expression [18]:
$D_{\pi}^{\alpha} f(x)=\left\{\begin{array}{l}\frac{1}{\Gamma_{(1-\alpha)}} \int_{0}^{x}(x-\xi)^{-\alpha-1}(f(\xi)-f(0)) d \xi, \alpha<0 \\ \frac{1}{\Gamma_{(1-\alpha)}} \frac{d}{d x} \int_{0}^{x}(x-\xi)^{-\alpha}(f(\xi)-f(0)) d \xi, 0<\alpha<1 \\ f^{(\mathrm{n})}((x))^{(\alpha-n)} \quad, n \leq \alpha<n+1<, n \geq 1\end{array}\right.$

Some properties of the proposed Modified Riemann-Liouville Derivative are listed in [18] as follows:

b) $\quad D_{\pi}^{@}(f(x) g(x))=f(x) D_{\pi}^{\alpha}(g(x))+g(x) D_{\pi}^{\alpha}(f(x))$
c) $D_{N}^{\alpha} f[g(x)]=f_{g}^{\circ}[g(x)] D_{x}^{\alpha} g(x)=D_{N}^{\alpha} f[g(x)](g(x))^{\alpha}$
d) $\mathbb{D}_{\mathrm{K}}^{\mathrm{a}} \mathrm{M}=0$, where M is any constant.

These equations play an important role in calculus.
We present the main steps of the generalizing fractional sub-equation method as:

Step 1: Give nonlinear FDEs with independent variables $\mathrm{X}=\left(x_{1}, x_{2}, x_{3}, \ldots, x_{\mathrm{w}}, \mathrm{t}\right)$ and dependent variable u :


Where $D_{\mathbb{t}}^{q} w_{s} D_{\mathbb{N}_{1}}^{\alpha} w_{v} D_{N_{2}}^{\alpha} u_{s} D_{N_{3}}^{\alpha} u$ and are modified fractional Riemann-liouville derivative of $u$ with
respect to $t, \mathrm{x}_{1}, \mathrm{~K}_{2}, \mathrm{x}_{1}, \ldots, \mathrm{x}_{\mathrm{m}}$ respectively and $\mathrm{u}=\left(\mathrm{x}_{1}, \mathrm{x}_{2}, \mathrm{x}_{1}, \ldots, \mathrm{x}_{\mathrm{m}}, \mathrm{t}\right)$ is unknown function, P is polynomial in u and its various partial derivative , in which the highest order derivatives and nonlinear terms are involved.

Step 2: By using the traveling wave transformation:
$\mathrm{u}\left(\mathrm{x}_{1}, \mathrm{x}_{2}, \mathrm{x}_{\mathrm{a}} \ldots \ldots, \mathrm{x}_{\mathrm{m}}, \mathrm{t}\right)=\mathrm{U}(\mathrm{\xi}) \quad, \xi=\mathrm{k}_{1} \mathrm{x}_{1}+\mathrm{k}_{2} \mathrm{x}_{2}+\mathrm{k}_{\mathrm{B}} \mathrm{x}_{\mathrm{g}}+\ldots \ldots+\mathrm{k}_{\mathrm{m}} \mathrm{x}_{\mathrm{m}}+\mathrm{ct}$

Where $c, k_{1}, k_{2}, k_{\mathrm{a}} \ldots, \mathrm{k}_{\mathrm{m}}$, are constants to be determined later, the FDE (5) is reduced to the nonlinear fractional ordinary differential equation (FODE)for $\mathrm{U}=\mathrm{G} \quad \mathrm{F}$ )


Step 3: Suppose the reduced equation obtained in Step 2 has a solution in the form
$\mathrm{U}(\xi)=\sum_{i=0} \mathrm{a}_{\mathrm{i}} \varphi^{i}$

Where $\mathrm{a}_{\mathrm{i}}(\mathrm{i}=0,1,2, \ldots, \mathrm{n})$ are constants to be determined later, n is a positive integer

Determined by balancing the highest order derivative and nonlinear terms in Eq. (5) or

Eq.(7)and $\varphi=\varphi($ (9) satisfies the following fractional Riccati equation:
$D_{\S}^{G} \varphi=\sigma+\varphi^{2}, 0<\alpha \leq 1$, where $\sigma$ is a constant
The following solutions of fractional Riccati equation (9):
$\varphi(\xi)=\left\{\begin{array}{cl}-\sqrt{-\sigma} \tanh _{a}(\sqrt{-\sigma} \xi), \sigma<0 \\ -\sqrt{-\sigma} \operatorname{coth}_{a}(\sqrt{-\sigma} \xi) & , \sigma<0 \\ \sqrt{\sigma} \tan _{a}(\sqrt{\sigma} \xi) & , \sigma>0 \\ -\sqrt{\sigma} \cot _{a}(\sqrt{\sigma} \xi), \sigma>0 \\ -\frac{\pi(1+\alpha)}{\xi m_{+w}}, w=\text { constant. } \sigma=0\end{array}\right.$

Where the generalized hyperbolic and trigonometric functions are defined by the Mittage-Leffler function :



$$
\tan _{\alpha}(x)=\frac{\sin _{a}(x)}{\cos _{\pi x}(x)} \quad, \quad \cot _{a}(x)=\frac{\cos _{\mathrm{a}}(x)}{\sin _{a x}(x)} \quad, \quad \operatorname{coth}_{a}(x)=\frac{\cosh _{\mathrm{ar}}(x)}{\sinh }
$$

## Remark:

We define the degree of $u(\xi)$ as $D[u(\xi)]=n$, which gives rise to the degrees of other expressions, as follows:
$D\left[\frac{d q_{u}}{d q \xi}\right]=n+q, D\left[u^{p}\left(\frac{d q u}{d q \xi}\right)^{r}\right]=n p+r(q+n)$.

So, the value of n can be obtained for the equation ( 5 or7).
Step 4: Substituting Eq.(8) along with Eq.(9) into Eq.(7), we can get a polynomial
in $\varphi(\xi)$, setting all the coefficients of $\varphi^{k}(\mathrm{k}=0,1, \ldots \mathrm{n})$ to zero, yields a set of overdetermined nonlinear algebraic equations for $\mathrm{c}, \mathrm{k}_{\mathrm{i}}$ and $\mathrm{a}_{\mathrm{i}}(\mathrm{i}=0,1,2, \ldots, \mathrm{n})$.

Step 5: Assuming that the constants $\mathrm{c}, \mathrm{k}, \mathrm{a}_{\mathrm{i}}(\mathrm{i}=0,1,2, \ldots, \mathrm{n}) \quad$ can be obtained by
solving the algebraic equations in step 4, substituting these constants and the solutions
of Eq.(9) into Eq. (8) we can obtain the explicit solutions of Eq.(5) immediately.

## 3 Application of the Method:

In this section, we want to solve some systems of non-linear fractional derivative differential equations by applying the technique of generalizing fractional sub-equation method.

## 1. Space-Time (1+1) fractional derivative Whitham-Broer-Kaup equations (WBK): [22,23]

We consider fractional derivative Whitham -Broer- Kaup equations in the form:

By considering the traveling wave transformation,
$\mathrm{u}(\mathrm{x}, \mathrm{t})=\mathrm{U}(\xi), \quad \mathrm{v}(\mathrm{x}, \mathrm{t})=\mathrm{V}(\xi), \quad$ where $\xi=\mathrm{kx}+\mathrm{ct}$

Eq. (11) can be reduced to the following nonlinear fractional ODE:

We suppose that Eq.(4.2) has the following general solution:

$$
\left\{\begin{array}{l}
U(k)=\sum_{i=0}^{n} a_{i} \varphi^{i} \\
V(k)=\sum_{i=0}^{m} b_{j} \varphi^{j}
\end{array}\right.
$$

By balancing the highest order derivative term and nonlinear term in Eq.(12),


Then we suppose that Eq.(12) has the following formal solution:

$$
\left\{\begin{array}{c}
U(k)=a_{0}+a_{1} \varphi \\
V(k)=b_{0}+b_{1} \varphi+b_{2} \varphi^{2} \tag{13}
\end{array}\right.
$$

Where $\varphi(5)$ satisfies fractional Riccati equation

$$
D_{\xi}^{\alpha} \varphi=\sigma+\varphi^{2}
$$

Substituting (13) along with (14) into (12) and setting the coefficient of $\varphi(6)^{\mathrm{i}}(\mathrm{i}=0,1,2,3)$ to zero, we can obtain aset of algebraic equation for $c, k, b_{0}, b_{1}, b_{2}, a_{0}$ and $a_{1}$ as follows

From the first equation of previous system (13):
$\varphi(\overline{4})^{\sigma_{0}} C^{\alpha} a_{1} \sigma+K^{\alpha} a_{0} a_{1} \sigma+K^{\alpha} \alpha b_{1}=0$
$\left.\varphi()^{1}\right)^{1} 2 k^{\alpha} b_{2} \sigma+2 \beta k^{2 \pi} a_{1} \sigma+k^{\alpha} a_{1}{ }_{1} 2 \sigma=0$
$\varphi(c)^{2}: C^{a_{2}} a_{1}+b_{1} K^{\alpha_{1}}+a_{1} k^{a^{a}} a_{0}=0$

From the second equation of previous system (13):

$\varphi(\overline{)})^{1}: 2 a c^{\alpha} b_{2}+k^{\alpha}\left(2 b_{2} a_{0} \sigma+2 b_{1} a_{1} \sigma\right)-2 \beta k^{2 \alpha} b_{1} \sigma=0$
$\left.\varphi()^{2}\right)^{a} c^{\alpha} b_{1}+k^{\alpha}\left(a_{0} b_{1}+2 a_{1} b_{2} \sigma+b_{0} a_{1}\right)+8 \gamma k^{2 a_{a_{1}} \sigma}-8 \beta k^{2 \pi} b_{2} \sigma=0$

By using Mathematica:
Case 1: $\left\{a_{1} \rightarrow 0, b_{1} \rightarrow 0, b_{2} \rightarrow 0\right\}$, where $a_{0}$ and $b_{0}$ are arbitrary.

$$
\left\{\begin{array}{l}
\mathrm{U}_{1}=a_{0} \\
\mathrm{w}_{1}=b_{0}
\end{array}\right.
$$

## Case

$$
\begin{aligned}
& \left\{a_{0} \rightarrow-c^{\alpha} k^{-\alpha \alpha_{v}} a_{1} \rightarrow 2 k^{\alpha} \sqrt{\beta^{2}+\gamma}, b_{0} \rightarrow 2\left(-k^{2 \alpha} \beta^{2} \sigma-k^{2 \alpha} \gamma \sigma-k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma \sigma}\right), b_{1} \rightarrow 0, b_{2} \rightarrow\right. \\
& \left.2: 2\left(-k^{2 \alpha} \beta^{2}-k^{2 \alpha} \gamma-k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma}\right)\right\}
\end{aligned}
$$

Where $\quad \sigma<0, \quad \xi=x k+c t$

$$
\begin{gathered}
\left\{\begin{array}{c}
U_{2}=-c^{\alpha} k^{-\alpha}-2 k^{\alpha} \sqrt{\beta^{2}+\gamma}\left(\sqrt{-\sigma} \tanh _{\alpha}(\sqrt{-\sigma} \xi)\right) \\
V_{2}=2\left(-k^{2 \alpha} \beta^{2} \sigma-k^{2 \alpha} \gamma \sigma-k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma \sigma}\right)+2\left(-k^{2 \alpha} \beta^{2}-k^{2 \alpha} \gamma-k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma}\right) \sigma \tanh _{\alpha}^{2}(\sqrt{-\sigma} \xi)
\end{array}\right. \\
\left\{\begin{array}{c}
U_{3}=-c^{\alpha} k^{-\alpha}-2 k^{\alpha} \sqrt{\beta^{2}+\gamma}\left(\sqrt{-\sigma} \operatorname{coth}_{\alpha}(\sqrt{-\sigma} \xi)\right) \\
V_{2}=2\left(-k^{2 \alpha} \beta^{2} \sigma-k^{2 \alpha} \gamma \sigma-k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma \sigma}\right)+2\left(-k^{2 \alpha} \beta^{2}-k^{2 \alpha} \gamma-k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma}\right) \sigma \operatorname{coth}_{\alpha}^{2}(\sqrt{-\sigma} \xi)
\end{array}\right.
\end{gathered}
$$

Where $\quad \sigma>0, \quad \xi=\mathrm{xk}+\mathrm{ct}$

$$
\begin{gathered}
\left\{\begin{array}{c}
\mathbb{U}_{4}=-c^{\alpha} k^{-\alpha}+2 k^{\alpha} \sqrt{\beta^{2}+\gamma}\left(\sqrt{\sigma} \tan _{\alpha}(\sqrt{\sigma} \xi)\right) \\
V_{4}=2\left(-k^{2 \alpha} \beta^{2} \sigma-k^{2 \alpha} \gamma \sigma-k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma \sigma}\right)+2\left(-k^{2 \alpha} \beta^{2}-k^{2 \alpha} \gamma-k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma}\right) \sigma \tan _{\alpha}{ }^{2}(\sqrt{\sigma} \xi)
\end{array}\right. \\
\left\{\begin{array}{c}
U_{5}=-c^{\alpha} k^{-\alpha}-2 k^{\alpha} \sqrt{\beta^{2}+\gamma}\left(\sqrt{\sigma} \cot _{\alpha}(\sqrt{\sigma} \xi)\right) \\
V_{5}=2\left(-k^{2 \alpha} \beta^{2} \sigma-k^{2 \alpha} \gamma \sigma-k^{2 \alpha} \beta \sqrt{\left.\beta^{2}+\gamma \sigma\right)}+2\left(-k^{2 \alpha} \beta^{2}-k^{2 \alpha} \gamma-k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma}\right) \sigma \cot _{\alpha}^{2}(\sqrt{\sigma} \xi)\right.
\end{array}\right.
\end{gathered}
$$

Where $\quad \sigma=0, \quad \xi=x k+c t, \mathrm{w}$ is constant.

$$
\left\{\begin{array}{c}
U_{6}=-c^{\alpha^{\alpha}} k^{-\alpha}-2 k^{\alpha} \sqrt{\beta^{2}+\gamma}\left(\frac{\pi(1+\alpha)}{g \alpha_{+w}}\right) \\
V_{6}=2\left(-k^{2 \alpha} \beta^{2}-k^{2 \alpha} \gamma-k^{2 \alpha} \beta \sqrt{\left.\beta^{2}+\gamma\right)\left(\frac{\pi(1+\alpha)}{g^{\alpha}+w}\right.}\right)^{2}
\end{array}\right.
$$

## Case3:

$\left\{a_{0} \rightarrow-c^{\alpha} k^{-a_{s}} a_{1} \rightarrow-2 k^{\alpha} \sqrt{\beta^{2}+\gamma}, b_{0} \rightarrow 2\left(-k^{2 \alpha} \beta^{2} \sigma-k^{2 \alpha} \gamma \sigma+k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma \sigma}\right), b_{1} \rightarrow 0, b_{2} \rightarrow\right.$ $\left.2\left(-k^{2 \alpha} \beta^{2}-k^{2 \alpha} \gamma+k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma}\right\}\right\}$

Where $\quad \sigma<0, \xi=x k+c t$

$$
\begin{gathered}
\left\{\begin{array}{c}
\mathbb{U}_{\gamma}=-c^{\alpha} k^{-\alpha}+2 k^{\alpha} \sqrt{\beta^{2}+\gamma}\left(\sqrt{-\sigma} \tanh _{\alpha}(\sqrt{-\sigma} \xi)\right) \\
\mathbb{V}_{\gamma}=2\left(-k^{2 \alpha} \beta^{2} \sigma-k^{2 \alpha} \gamma \sigma+k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma \sigma}\right)+2\left(-k^{2 \alpha} \beta^{2}-k^{2 \alpha} \gamma+k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma}\right)\left(\sigma \tanh _{\alpha}^{2}(\sqrt{-\sigma} \xi)\right.
\end{array}\right. \\
\left\{\begin{array}{c}
U_{Q}=-c^{\alpha} k^{-\pi}+2 k^{\alpha} \sqrt{\beta^{2}+\gamma}\left(\sqrt{-\sigma} \operatorname{coth}_{\alpha}(\sqrt{-\sigma} \xi)\right) \\
V_{\Omega}=2\left(-k^{2 \alpha} \beta^{2} \sigma-k^{2 \alpha} \gamma \sigma+k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma \sigma}\right)+2\left(-k^{2 \alpha} \beta^{2}-k^{2 \alpha} \gamma+k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma}\right)\left(\sigma \operatorname{coth}^{2}(\sqrt{-\sigma} \xi)\right.
\end{array}\right.
\end{gathered}
$$

Where $\quad \sigma>0, \xi=x k+c t$
$\left\{\begin{array}{c}U_{9}=-c^{\alpha} k^{-\alpha}-2 k^{\alpha} \sqrt{\beta^{2}+\gamma}\left(\sqrt{\sigma} \tan _{\alpha}(\sqrt{\sigma} \xi)\right) \\ V_{9}=2\left(-k^{2 \alpha} \beta^{2} \sigma-k^{2 \alpha} \gamma \sigma+k^{2 \alpha} \beta \sqrt{\left.\beta^{2}+\gamma \sigma\right)}+2\left(-k^{2 \alpha} \beta^{2}-k^{2 \alpha} \gamma+k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma}\right)\left(\sigma \tan _{\alpha}^{2}(\sqrt{\sigma} \xi)\right.\right.\end{array}\right.$
$\left\{\begin{array}{c}U_{10}=-c^{\alpha} k^{-\alpha}+2 k^{\alpha} \sqrt{\beta^{2}+\gamma}(\sqrt{\sigma} \cot (\sqrt{\sigma} \xi)) \\ V_{10}=2\left(-k^{2 \alpha} \beta^{2} \sigma-k^{2 \alpha} \gamma \sigma+k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma \sigma}\right)+2\left(-k^{2 \alpha} \beta^{2}-k^{2 \alpha} \gamma+k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma}\right)\left(\sigma \cot ^{2}(\sqrt{\sigma} \xi)\right.\end{array}\right.$

Where $\sigma=0, \quad \xi=x k+c t, \mathrm{w}$ is constant.

$$
\left\{\begin{array}{c}
U_{11}=-c^{\alpha} k^{-\alpha}+2 k^{\alpha} \sqrt{\beta^{2}+\gamma}\left(\frac{r(1+\alpha)}{k \pi}+w\right) \\
V_{11}=2\left(-k^{2 \alpha} \beta^{2}-k^{2 \alpha} \gamma-k^{2 \alpha} \beta \sqrt{\beta^{2}+\gamma}\right)\left(\frac{r(1+\alpha)}{k \pi+w}\right)^{2}
\end{array}\right.
$$

### 1.1 Figures of Space-Time (1+1) fractional derivative Whitham -Broer- Kaup equations:

Case 2:
Where $\sigma<0$, Let $\alpha=\mathrm{c}=\mathrm{k}=\beta=1_{v} \sigma=-1_{v} \gamma=0$,then:


Where $\sigma>0$, Let $\alpha=\mathrm{c}=\mathrm{k}=\beta=\sigma=1_{s} \gamma=0$, then:



Where $\sigma=0$, Let $\alpha=\mathrm{c}=\mathrm{k}=\beta=1$, $\mathrm{w}=\gamma=0$, the


## Case 3:

Where $\sigma<0$, Let $\alpha=\mathrm{c}=\mathrm{k}=\beta=1_{s} \sigma=-1_{s} \gamma=0$, then:


Where $\alpha>0$, Let $\alpha=c=k=\beta=\sigma=1_{s} \gamma=0$, then:


Where $\sigma=0$, Let $\alpha=\mathrm{c}=\mathrm{k}=\beta=1_{s} \gamma=w=0$ then:


2:Space-Time (2+1) fractional derivative Breaking Soliton equations:[18]
We consider the Space-time ( $2+1$ ) fractional Breaking Soliton equations:


By considering the traveling wave transformation

$$
u(x, t)=U(\xi) \quad, v(x, t)=V(\xi) \quad, \quad \text { Where } \xi=k_{1} x+k_{2} y+c t
$$

Eq.(15), can be reduced to the following nonlinear fractional ODE:

We suppose that Eq.(16) has the following general solution:

$$
\left\{\begin{array}{l}
U(k)=\sum_{i=0}^{n} a_{i} \varphi^{i} \\
V(k)=\sum_{i=0}^{m} b_{j} \varphi^{j}
\end{array}\right.
$$

By balancing the highest order derivative term and nonlinear term in Eq.(16),


Then we suppose that Eq.(4.6) has the following formal solution:

$$
\left\{\begin{array}{l}
\mathrm{U}(\mathrm{l})=a_{0}+a_{1} \varphi+a_{2} \varphi^{2}  \tag{17}\\
\mathrm{~V}(\mathrm{~g})=b_{0}+b_{1} \varphi+b_{2} \varphi^{2}
\end{array}\right.
$$

Substituting (17) along with (14) into (16) and setting the coefficient of $\varphi\left(\mathrm{C}^{\mathrm{i}}\right)^{\mathrm{i}}(\mathrm{i}=0,1,2,3,4,5)$ to zero, we can obtain a set of algebraicequation for $c, k, b_{1}, b_{0}, b_{2}, a_{0}, a_{1}$ and $a_{2}$ as follows:

From the first equation of previous system (15):

$$
\begin{aligned}
& \varphi(t)^{0}{ }^{0} c^{a} a_{1} \sigma+2 a k_{1}{ }^{2 a_{k}} k_{2}{ }^{a} a_{1} \sigma^{n} 2+4 k_{1}{ }^{\alpha} a\left(b_{1} \sigma a_{0}+a_{1} \sigma b_{0}\right)=0 \\
& \varphi\left(()^{1}\right)^{2} 2 c^{a} a_{2} \sigma+16 a k_{1}{ }^{2 a_{k}} k_{2}{ }^{a} a_{2} \sigma^{2}+4 a k_{1}{ }^{\alpha}\left(2 b_{2} \sigma a_{0}+2 a_{1} \sigma b_{1}+2 b_{0} \sigma a_{2}\right)=0 \\
& \varphi(द)^{2} c^{\alpha} a_{1}+8 a k_{1}{ }^{2 \alpha} k_{2}{ }^{\alpha} a_{1} \sigma+4 a k_{1}{ }^{\alpha}\left(a_{0} b_{1}+3 a_{1} b_{2} \sigma+3 a_{2} b_{1} \sigma+b_{0} a_{1}\right)=0 \\
& \varphi(\varepsilon)^{a_{3}}: 2 a_{2} c^{\alpha}+40 a k_{1}{ }^{2 a_{k}} k_{2}{ }^{\alpha_{2}} a_{2}+4 k_{1}{ }^{\alpha} a\left(2 b_{2} a_{0}+2 b_{1} a_{1}+2 a_{2} b_{2} \sigma+2 b_{0} a_{2}+2 a_{2} b_{2} \sigma\right)=0 \\
& \varphi(5)^{4}: 6 \mathrm{k}_{1}{ }^{2 \mathrm{a}_{2}} \mathrm{k}_{2}{ }^{a_{a_{1}}}+4 \mathrm{k}_{1}{ }^{{ }^{a}} \mathrm{a}\left(3 b_{2} \mathrm{a}_{1}+3 \mathrm{~b}_{1} \mathrm{a}_{2}\right)=0 \\
& \varphi(5)^{5}: 24 a_{2} k_{1}{ }^{2 \alpha_{2}}{ }^{\alpha}{ }^{a}+4 k_{1}{ }^{\alpha} a\left(4 a_{2} b_{2}\right)=0
\end{aligned}
$$

From the second equation of previous system (15):
$\varphi(\xi)^{0_{:}} \mathrm{ak}_{2}{ }^{\alpha}{ }^{a_{1}}-b_{1} \sigma k_{1}{ }^{a}=0$

$\varphi\left(\mathrm{c}^{2}\right)^{2} \mathrm{a}_{1} \mathrm{k}_{2}{ }^{\alpha}-\mathrm{k}_{1}{ }^{\alpha_{1}} \mathrm{~b}_{1}=0$
$\varphi\left(\mathrm{c}^{1)^{3}} 2 \mathrm{a}_{2} \mathrm{k}_{2}{ }^{\circledR}-2 \mathrm{k}_{1}{ }^{{ }^{[ }} \mathrm{b}_{2}=0\right.$

By using Mathematica :

Case1: $\left\{a_{1} \rightarrow 0, a_{2} \rightarrow 0, b_{2} \rightarrow 0, b_{1} \rightarrow 0\right\}$
$\mathrm{U}_{1}=\mathrm{a}_{0}$
$\mathrm{V}_{1}=\mathrm{b}_{0}$


Where $\sigma<0, \quad \xi=\mathrm{xk}_{1}+\mathrm{yk}_{2}+$ ct

$$
\begin{gathered}
\left\{\begin{array}{c}
\mathbb{U}_{2}=a_{0}-\frac{3}{2} k_{1}^{2 \alpha} \sigma \tanh _{\alpha}^{2}(\sqrt{-\sigma} \xi) \\
V_{2}=-\frac{k_{1}^{-\alpha}\left(c^{\alpha}+4 a a_{0} k_{2}^{\alpha}+8 a \sigma k_{1}^{2 \alpha} k_{2}^{\alpha}\right)}{4 a}-\frac{3}{2} k_{1}^{\alpha} k_{2}^{\alpha} \sigma \tanh h_{a}^{2}(\sqrt{-\sigma} \xi)
\end{array}\right. \\
\left\{\begin{array}{c}
U_{a}=a_{0}-\frac{3}{2} k_{1}^{2 \alpha} \sigma \operatorname{coth}_{\alpha}^{2}(\sqrt{-\sigma} \xi) \\
V_{a}=-\frac{k_{1}^{-\alpha}\left(c^{\alpha}+4 a a_{0} k_{2}^{\alpha}+8 a \sigma k_{1}^{2 \alpha} k_{2}^{\alpha}\right)}{4 a}-\frac{3}{2} k_{1}^{\alpha} k_{2}^{\alpha} \sigma \operatorname{coth}_{\alpha}{ }^{2}(\sqrt{-\sigma} \xi)
\end{array}\right.
\end{gathered}
$$

Where $\sigma>0, \xi=\mathrm{xk}_{1}+\mathrm{yk}_{2}+\mathrm{ct}$

$$
\begin{gathered}
\left\{\begin{array}{c}
U_{4}=a_{0}-\frac{3}{2} k_{1}^{2 \alpha} \sigma \tan _{\alpha}^{2}(\sqrt{\sigma} \xi) \\
V_{4}=-\frac{k_{1}^{-\alpha}\left(c^{\alpha}+4 a a_{0} k_{2}^{\alpha}+8 a \sigma k_{1}^{2 \alpha} k_{2}^{\alpha}\right)}{4 a}-\frac{3}{2} k_{1}^{\alpha} k_{2}^{\alpha} \sigma \tan _{\alpha}^{2}(\sqrt{\sigma} \xi)
\end{array}\right. \\
\left\{\begin{array}{c}
U_{5}=a_{0}-\frac{3}{2} k_{1}^{2 \alpha} \sigma \cot _{a}^{2}(\sqrt{\sigma} \xi) \\
V_{5}=-\frac{k_{1}^{-\alpha}\left(c^{\alpha}+4 a a_{0} k_{2}^{\alpha \alpha}+8 a \sigma k_{1}^{2 \alpha} k_{2}^{\alpha}\right)}{4 a}-\frac{3}{2} k_{1}^{\alpha} k_{2}^{\alpha} \sigma \cot _{\alpha}^{2}(\sqrt{\sigma} \xi)
\end{array}\right.
\end{gathered}
$$

Where $\sigma=0, \xi=\mathrm{xk}_{1}+\mathrm{yk}_{2}+\mathrm{ct}$

## 2.1: Figures of Space-Time (2+1) fractional derivative Breaking Soliton equations:

Case 2:

Where $\sigma<0$, Let $\mathrm{a}_{0}=\alpha=\mathrm{c}=\mathrm{k}=1_{v} \sigma=-1_{v} \gamma=0$, then:


Where $\sigma>0$, Let $\alpha=\mathrm{c}=\mathrm{k}=\beta=\mathrm{a}=\sigma=1, \gamma=0$, then:


Where $\sigma=0$, Let $\alpha=c=k=\beta=1$, $w=\gamma=0$, then:


3: Space-Time (1+1) fractional derivative Coupled Boussinesq-Burgers equations:
We consider the Space-Time fractional Coupled Boussinesq-Burgers equations:

$$
\left\{\begin{array}{c}
D_{t}^{\alpha} u-\frac{1}{2} D_{\pi}^{\alpha} v+2 u D_{s}^{\alpha} u=0  \tag{18}\\
D_{t}^{\alpha} v-\frac{1}{2} D_{x}^{Z \alpha} u+2 D_{s}^{\alpha}(u v)=0
\end{array} \quad 0<\alpha \leq 1\right.
$$

By considering the traveling wave transformation
$\mathrm{u}(\mathrm{x}, \mathrm{t})=\mathrm{U}(\xi), \quad \mathrm{v}(\mathrm{x}, \mathrm{t})=\mathrm{V}(\xi), \quad$ Where $\xi=\mathrm{K} \mathrm{x}+\mathrm{ct}$

Eq.(18) can be reduced to the following nonlinear fractional ODE:

We suppose that Eq.(19) has the following general solution:

$$
\left\{\begin{array}{l}
U(\xi)=\sum_{i=0}^{n} a_{i} \varphi^{i} \\
V(\xi)=\sum_{j=0}^{m} b_{j} \varphi^{j}
\end{array}\right.
$$

By balancing the highest order derivative term and nonlinear term in Eq.(19) $\mathbb{D}_{\xi}{ }^{G} \mathrm{~V}, \mathrm{UD}_{\xi}^{\mathbb{G}} \mathrm{U}$ and
$D^{\text {axa }} \mathbb{U}, D_{g}^{\alpha}(V U)$, we have $n+3=n+m+1$ then $m=2,1+2 n=m+1$ then $n=1$.

Then we suppose that Eq .(19) has the following formal solution:

$$
\left\{\begin{array}{c}
U(\xi)=a_{0}+a_{1} \varphi  \tag{20}\\
V(\xi)=b_{0}+b_{1} \varphi+b_{2} \varphi^{2}
\end{array}\right.
$$

Substituting (20) along with (14) into (19) and setting the coefficient of $\varphi\left({ }^{(6)}\right)^{\mathrm{i}}(\mathrm{i}=0,1,2,3,4)$ to zero, we can obtain a set of algebraic equation for $c, k, b_{0,}, b_{1}, b_{2}, a_{0}$ and $a_{1}$ as follows:

From the first equation of previous system (19):
$\varphi(5)^{0} * c^{\alpha} * a_{1} * \sigma-\frac{1}{2} * k^{\alpha} * b_{1} * \sigma+2 * k^{\alpha} * a_{0} * a_{1} * \sigma=0$
$\varphi(\mathrm{c})^{1}{ }^{1}-\mathrm{k}^{\alpha} * \mathrm{~b}_{2} * \sigma+2 \mathrm{k}^{\mathrm{a}} * \sigma * \mathrm{a}_{1}{ }^{2}=0$
$\varphi(c)^{2}: c^{\alpha} * a_{1}-\frac{1}{2} * k^{\alpha} * b_{1}+2 * k^{\alpha} * a_{0} * a_{1}=0$
$\varphi(\varepsilon)^{a}:-k^{\alpha} * b_{2}+2 * k^{\alpha} * a_{1}{ }^{\wedge} 2=0$

From the second equation of previous system (19):
$\varphi(\overline{ })^{0}: c^{\alpha} * b_{1} * \sigma-k^{3 a} * a_{1} * \sigma^{\wedge} 2+2 k^{\alpha} *\left(a_{0} * b_{1} * \sigma+b_{0} * a_{1} * \sigma\right)=0$
$\varphi\left({ }^{1}\right)^{1}: 2 * \sigma * c^{\alpha} * b_{2}+4 * a_{0} * \sigma * k^{\alpha} * b_{2}+2 k^{\alpha} *\left(a_{1} * b_{1} * \sigma+b_{1} * a_{1} * \sigma\right)=0$
$\varphi(\bar{b})^{2} * c^{a} * b_{1}-4 k^{2 a} * a_{1} * \sigma+2 k^{a} *\left(a_{0} * b_{1}+3 b_{2} * a_{1} * \sigma+b_{0} * a_{1}\right)=0$
$\varphi(\overline{)})^{a_{2}} 2 * c^{a} * b_{2}+4 k^{a} * b_{2} * a_{0}+4 k^{a} * a_{1} * b_{1}=0$
$\varphi(\mathrm{g})^{4}:-3 \mathrm{k}^{7 a} * \mathrm{a}_{1}+6 \mathrm{k}^{a} * \mathrm{a}_{1} * b_{2}=0$

By usingMathematica:
Case1: $\left\{b_{1} \rightarrow 0, a_{1} \rightarrow 0, b_{2} \rightarrow 0\right\}$
$\left\{\begin{array}{l}\mathrm{U}_{1}=\mathrm{a}_{0} \\ \mathrm{~W}_{1}=\mathrm{b}_{0}\end{array}\right.$

Case2: $\left\{b_{1} \rightarrow 0, b_{0} \rightarrow \frac{1}{2} k^{2 \alpha_{\sigma_{s}}} a_{1} \rightarrow-\frac{k^{k \pi}}{2}, a_{0} \rightarrow-\frac{1}{2} c^{a^{\pi}} k^{-a}{ }_{v} b_{2} \rightarrow \frac{k^{2 \pi}}{2}\right\}$

Where $\sigma<0, \xi=x k+c t$
$\left\{\begin{array}{c}\mathbb{U}_{2}=-\frac{1}{2} c^{\alpha^{\alpha}} k^{-\alpha}-\frac{k^{\alpha}}{2}\left(\sqrt{-\sigma} \tanh _{\alpha}(\sqrt{-\sigma} \xi)\right) \\ \mathbb{V}_{2}=\frac{1}{2} k^{2 \pi} \sigma+\frac{k^{2 \alpha}}{2} \sigma \tanh _{\alpha}^{2}(\sqrt{-\sigma} \xi)\end{array}\right.$
$\left\{\begin{array}{c}U_{2}=-\frac{1}{2} c^{\alpha} k^{-\pi}-\frac{k^{\alpha}}{2} \sqrt{-\sigma} \operatorname{coth}_{\alpha}(\sqrt{-\sigma} \xi) \\ V_{0}=\frac{1}{2} k^{2 \pi} \sigma+\frac{k^{2 \alpha}}{2} \sigma \operatorname{coth}_{\alpha}^{2}(\sqrt{-\sigma} \xi)\end{array}\right.$
Where $\sigma>0, \xi=x k+c t$
$\left\{\begin{array}{l}U_{4}=-\frac{1}{2} c^{\alpha} k^{-\alpha}+\frac{k^{\alpha}}{2} \sqrt{\sigma} \tan _{\alpha}(\sqrt{\sigma} \xi) \\ V_{4}=\frac{1}{2} k^{2 \pi} \sigma+\frac{k^{2 \alpha}}{2} \sigma \tan _{\alpha}^{2}(\sqrt{\sigma} \xi)\end{array}\right.$
$\left\{\begin{array}{l}U_{5}=-\frac{1}{2} c^{\alpha} k^{-\alpha}-\frac{k^{\alpha}}{2}(\sqrt{\sigma} \cot (\sqrt{\sigma} \xi) \\ V_{5}=\frac{1}{2} k^{2 \alpha} \sigma+\frac{k^{2 \alpha}}{2} \sigma \cot _{\alpha}^{2}(\sqrt{\sigma} \xi)\end{array}\right.$

Where $\sigma=0, \xi=\mathrm{xk}+\mathrm{ct}$
$\left\{\begin{array}{c}U_{6}=-\frac{1}{2} c^{\alpha} k^{-\alpha}-\frac{\mathbb{k}^{m}}{2}\left(\frac{\Gamma(1+\omega)}{k \pi}+w\right) \\ V_{6}=\frac{k^{2 \pi}}{2}\left(\left(\frac{\pi(1+\alpha)}{k \pi}+w\right)\right)^{2}\end{array}\right.$

Case3: $\left\{b_{1} \rightarrow 0, b_{0} \rightarrow \frac{1}{2} k^{2 \pi} \sigma_{v} a_{1} \rightarrow \frac{k^{m}}{2}, a_{0} \rightarrow-\frac{1}{2} c^{\alpha^{\alpha}} k^{-a_{s}}{ }_{v} b_{2} \rightarrow \frac{k^{2 \pi}}{2}\right\}$

Where $\sigma<0, \xi=x k+c t$
$\left\{\begin{array}{c}\mathbb{U}_{7}=-\frac{1}{2} c^{\alpha^{\alpha}} k^{-\alpha}+\frac{k^{\alpha}}{2}\left(\sqrt{-\sigma} \tanh _{\alpha}(\sqrt{-\sigma} \xi)\right) \\ \mathbb{W}_{7}=\frac{1}{2} k^{2 \alpha} \sigma+\frac{k^{2 \alpha}}{2} \sigma \tanh _{\alpha}^{2}(\sqrt{-\sigma} \xi)\end{array}\right.$
$\left\{\begin{array}{c}\mathrm{U}_{8}=-\frac{1}{2} c^{\alpha} k^{-a}+\frac{k^{\alpha}}{2} \sqrt{-\sigma} \operatorname{coth}(\sqrt{-\sigma} \xi) \\ \mathrm{V}_{0}=\frac{1}{2} k^{2 \pi} \sigma+\frac{k^{2 \alpha}}{2} \sigma \operatorname{coth}_{\alpha}^{2}(\sqrt{-\sigma} \xi)\end{array}\right.$

Where $\sigma>0, \xi=x k+c t$
$\left\{\begin{array}{l}U_{9}=-\frac{1}{2} c^{\alpha} k^{-\alpha}-\frac{k^{\alpha}}{2} \sqrt{\sigma} \tan _{\alpha}(\sqrt{\sigma} \xi) \\ V_{9}=\frac{1}{2} k^{2 \alpha} \sigma+\frac{k^{2 \alpha}}{2} \sigma \tan _{\alpha}^{2}(\sqrt{\sigma} \xi)\end{array}\right.$
$\left\{\begin{array}{l}U_{10}=-\frac{1}{2} c^{\alpha} k^{-\alpha}+\frac{k^{\alpha}}{2}\left(\sqrt{\sigma} \cot _{\alpha}(\sqrt{\sigma} \xi)\right. \\ V_{10}=\frac{1}{2} k^{2 \alpha} \sigma+\frac{k^{2 \alpha}}{2} \sigma \cot _{\alpha}^{2}(\sqrt{\sigma} \xi)\end{array}\right.$

Where $\sigma=0, \xi=x k+c t$
$\left\{\begin{array}{c}U_{11}=-\frac{1}{2} c^{\alpha} k^{-\pi}+\frac{k^{\pi}}{2}\left(\frac{\Gamma(1+\alpha)}{k \pi}+w\right) \\ W_{11}=\frac{k^{2 \pi}}{2}\left(\left(\frac{\Gamma(1+a)}{k \pi}+w\right)\right)^{2}\end{array}\right.$
3.1 Figures of Space-Time (1+1) fractional derivative Coupled Boussinesq-Burgers equations:

Case 2:

Where $\sigma<0$, Let $\alpha=\mathrm{c}=\mathrm{k}=1_{s} \sigma=-1_{s} \mathrm{w}=0$, then:


Where $\sigma>0$, Let $\alpha=\mathrm{c}=\mathrm{k}=\beta=\sigma=1_{v} \gamma=0$, then:


Where $\sigma=0$, Let $\alpha=\mathrm{c}=\mathrm{k}=\beta=1_{v} w=\gamma=0$, then:


## Case 3:

Where $\sigma<0$, Let $\alpha=\mathrm{c}=\mathrm{k}=1_{s} \sigma=-1_{n}$ then


Where
$\sigma>0$ Let $\alpha=c=k=\beta=\sigma=1_{v} \gamma=0$


Where $\sigma=0$, Let $\alpha=c=k=\beta=1$, $w=\gamma=0$, then:


## 4: Space-Time (1+1) fractional derivative Coupled Burgers Equations.

We consider Space-Time fractional coupled Burgers Equations:

By considering the traveling wave transformation $\mathrm{u}(\mathrm{x}, \mathrm{t})=\mathrm{U}(\xi), \mathrm{v}(\mathrm{x}, \mathrm{t})=\mathrm{V}(\xi)$, and $\xi=\mathrm{xk}+\mathrm{ct}$
Eq.(21) can be reduced to the following nonlinear fractional ODE:

We suppose that Eq.(22) has the following general solution:

$$
\left\{\begin{array}{l}
U(\xi)=\sum_{i=0}^{n} a_{i} \varphi^{i} \\
V(\xi)=\sum_{j=0}^{m} b_{j} \varphi^{j}
\end{array}\right.
$$

By balancing the highest order derivative term and nonlinear term in Eq. (22) $D_{\xi}^{2 \pi} U, U D_{\xi}^{\pi} U a n d V D_{\xi}^{\alpha} V, D_{\xi}^{2 \pi} V$, we have $\mathrm{n}+2=\mathrm{n}+\mathrm{n}+1$ then $\mathrm{n}=1,2+\mathrm{m}=\mathrm{m}+\mathrm{m}+1$ then $\mathrm{m}=\mathrm{n}=1$.

Then we suppose that Eq.(22) has the following formal solution.
$\left\{\begin{array}{l}U(\xi)=a_{0}+a_{1} \varphi \\ V(\xi)=b_{0}+b_{1} \varphi\end{array}\right.$

Substituting (23) along with (14) into (22) and setting the coefficient of $\varphi(4)^{i}(\mathrm{i}=0,1,2,3)$
to zero, We can obtain a set of algebraic equation for $c, k, b_{0}, b_{1}, a_{0}$ and $a_{1}$ as follows:
From the first equation of previous system (22):
$\varphi(5)^{0}: c^{\alpha} a_{1} \sigma+2 k^{\alpha} a_{1} \sigma a_{0}+p k^{\alpha} a_{0} b_{1} \sigma+p k^{\varpi} b_{0} \sigma a_{1}=0$
$\varphi(\mathrm{k})^{1}{ }^{1}-2 k^{2 a_{a_{1}} \sigma+2 k^{\propto} \sigma a_{1}}{ }^{2}+2 p \sigma k^{\alpha_{1}} b_{1} a_{1}=0$

$\varphi(\xi)^{a_{s}}-2 k^{2 \alpha_{a_{1}}}+2 k^{\alpha_{a}^{2}}+2 p k^{\alpha} b_{1} a_{1}=0$
From the second equation of previous system (22):
$\varphi(5)^{\alpha_{3}} c^{\alpha} b_{1} \sigma+2 k^{\alpha} b_{1} \sigma b_{0}+q k^{\alpha} b_{0} a_{1} \sigma+q k^{\alpha_{0}} a_{0} \sigma b_{1}=0$
$\varphi(\mathrm{k})^{1:}-2 \sigma k^{2 \alpha_{a}} b_{1}+2 k^{\alpha} b_{1}^{2} \sigma+2 k^{\alpha} q^{b_{1}} a_{1} \sigma=0$
$\varphi(c)^{2}: c^{\alpha} b_{1}+2 k^{\alpha} b_{0} b_{1}+q k^{\alpha} b_{1} a_{0}+q k^{\alpha} b_{0} a_{1}=0$
$\varphi(\varepsilon)^{a_{s}}-2 k^{2 \alpha_{1}} b_{1}+k^{\alpha} 2 b_{1}{ }_{2} 2+2 k^{\alpha} q a_{1} b_{1}=0$

By using Mathematica:

Case1: $\left\{b_{1} \rightarrow 0, a_{1} \rightarrow 0\right\}$

$$
\left\{\begin{array}{l}
U_{1}=a_{0} \\
v_{1}=b_{0}
\end{array}\right.
$$

Case2: $\left\{b_{1} \rightarrow k^{\alpha}{ }_{v} b_{0} \rightarrow-\frac{1}{2} c^{\alpha_{0}} k^{-a_{v}}{ }_{v} a_{1} \rightarrow 0, a_{0} \rightarrow 0\right\}$

Where $\sigma<0, \xi=x k+c t$

$$
\begin{gathered}
\left\{\begin{array}{c}
\mathbb{U}_{2}=0 \\
\mathrm{~V}_{2}=-\frac{1}{2} c^{\alpha} k^{-\alpha}-k^{\alpha} \sqrt{-\sigma} \tanh _{\alpha}(\sqrt{-\sigma} \xi)
\end{array}\right. \\
\left\{\begin{array}{c}
\mathbb{U}_{3}=0 \\
V_{a}=-\frac{1}{2} c^{\alpha} k^{-\alpha}-k^{\alpha} \sqrt{-\sigma} \operatorname{coth}_{a}(\sqrt{-\sigma})
\end{array}\right.
\end{gathered}
$$

Where $\quad \sigma>0, \xi=x k+c t$

$$
\begin{aligned}
& \left\{\begin{array}{c}
\mathbb{U}_{4}=0 \\
V_{4}=-\frac{1}{2} c^{\alpha} k^{-\alpha}+k^{\alpha}\left(\sqrt{\sigma} \tan _{\alpha}(\sqrt{\sigma} \xi)\right.
\end{array}\right. \\
& \left\{\begin{array}{c}
U_{5}=0 \\
V_{5}=-\frac{1}{2} c^{\alpha} k^{-\alpha}-k^{\alpha} \sqrt{\sigma} \cot _{a}(\sqrt{\sigma} \xi)
\end{array}\right.
\end{aligned}
$$

Where $\sigma=0, \xi=\mathrm{xk}+\mathrm{ct}$, w is constant.

$$
\left\{\begin{array}{c}
\mathbb{U}_{6}=0 \\
V_{6}=-\frac{1}{2} c^{\alpha^{\alpha}} k^{-a}-\frac{k^{m} \Gamma(1+a)}{\xi^{3 x}+w}
\end{array}\right.
$$

$$
\text { Case3: }\left\{b_{1} \rightarrow 0, b_{0} \rightarrow 0, a_{1} \rightarrow k^{\alpha}{ }_{v} a_{0} \rightarrow-\frac{1}{2} c^{\alpha} k^{-a}\right\}
$$

Where $\sigma<0, \xi=\mathrm{xk}+\mathrm{ct}$

$$
\left\{\begin{array}{c}
\mathrm{U}_{7}=-\frac{1}{2} c^{\alpha} k^{-ब}-k^{\alpha} \sqrt{-\sigma} \tanh _{\alpha}(\sqrt{-\sigma} \xi) \\
\mathbb{W}_{7}=0
\end{array}\right.
$$

$\left\{\begin{array}{c}U_{\Omega}=-\frac{1}{2} c^{\alpha} k^{-\alpha}-k^{\alpha} \sqrt{-\sigma} \operatorname{coth}_{\pi}(\sqrt{-\sigma} \xi) \\ W_{\Omega}=0\end{array}\right.$
Where $\sigma>0, \xi=\mathrm{xk}+\mathrm{ct}$
$\left\{\begin{array}{c}\mathrm{U}_{9}=-\frac{1}{2} c^{\alpha^{\alpha}} k^{-\alpha}+k^{ब}\left(\sqrt{\sigma} \tan _{\alpha}(\sqrt{\sigma} \xi)\right. \\ \mathrm{V}_{9}=0\end{array}\right.$
$\left\{\begin{array}{c}U_{10}=-\frac{1}{2} c^{\alpha} k^{-\alpha}-k^{\alpha} \sqrt{\sigma} \cot (\sqrt{\alpha}(\sqrt{\xi}) \\ W_{10}=0\end{array}\right.$
Where $\sigma=0, \xi=\mathrm{xk}+\mathrm{ct}, \mathrm{w}$ is constant.
$\left\{\begin{array}{c}U_{11}=-\frac{1}{2} c^{\alpha} k^{-a}-k^{\left.\alpha \frac{\Gamma(1)}{k \pi}+w\right)} \\ W_{11}=0\end{array}\right.$


Where $\sigma<0, \xi=\mathrm{xk}+\mathrm{ct}$

$$
\begin{aligned}
& \left\{\begin{array}{l}
U_{12}=-\frac{c^{\alpha} k^{-\alpha}(-1+p)}{2(-1+p q)}-\frac{k^{\alpha}(-1+p)}{-1+p q}\left(\sqrt{-\sigma} \tanh _{\alpha}(\sqrt{-\sigma} \xi)\right. \\
\mathbb{V}_{12}=-\frac{c^{\alpha} k^{-\alpha}(-1+q)}{2(-1+p q)}-\frac{k^{\alpha}(-1+q)}{-1+p q}\left(\sqrt{-\sigma} \tanh _{\alpha}(\sqrt{-\sigma} \xi)\right)
\end{array}\right. \\
& \left\{\begin{array}{l}
U_{12}=-\frac{c^{\alpha} k^{-\alpha}(-1+p)}{2(-1+p q)}-\frac{k^{\alpha}(-1+p)}{-1+p q}\left(\sqrt{-\sigma} \operatorname{coth}_{\alpha}(\sqrt{-\sigma} \xi)\right. \\
\mathbb{v}_{12}=-\frac{c^{\alpha} k^{-\alpha}(-1+q)}{2(-1+p q)}-\frac{k^{\alpha}(-1+q)}{(-1+p q)}\left(\sqrt{-\sigma} \operatorname{coth}_{\alpha}(\sqrt{-\sigma} \xi)\right.
\end{array}\right.
\end{aligned}
$$

Where $\sigma>0, \xi=\mathrm{xk}+\mathrm{ct}$

$$
\begin{aligned}
& \left\{\begin{array}{l}
U_{14}=-\frac{c^{\alpha} k^{-\alpha}(-1+p)}{2(-1+p q)}+\frac{k^{\alpha}(-1+p)}{-1+p q}\left(\sqrt{\sigma} \tan _{\alpha}(\sqrt{\sigma} \xi)\right) \\
\mathbb{V}_{14}=-\frac{c^{\alpha} k^{-\alpha}(-1+q)}{2(-1+p q)}+\frac{k^{\alpha}(-1+q)}{-1+p q}\left(\sqrt{\sigma} \tan _{\alpha}(\sqrt{\sigma} \xi)\right)
\end{array}\right. \\
& \left\{\begin{array}{l}
U_{15}=-\frac{c^{\alpha} k^{-\alpha}(-1+p)}{2(-1+p q)}-\frac{k^{\alpha}(-1+p)}{-1+p q}\left(\sqrt{\sigma} \cot _{a}(\sqrt{\sigma} \xi)\right) \\
\mathbb{W}_{15}=-\frac{c^{\alpha} k^{-\alpha}(-1+q)}{2(-1+p q)}-\frac{k^{\alpha}(-1+q)}{(-1+p q)}(\sqrt{\sigma} \cot (\sqrt{\sigma} \xi))
\end{array}\right.
\end{aligned}
$$

Where $w=$ constant, $\sigma=0$ and $\xi=x k+c t$


## 4.1: Figures of Space-Time (1+1) fractional derivative Coupled Burgers Equations:

## Case 2:

Where $\sigma<0$, Let $\alpha=\mathrm{c}=\mathrm{k}=1, \sigma=-1$, then


Where $\sigma>0$, Let $\alpha=\mathrm{c}=\mathrm{k}=\sigma=1$, then:


Where $\sigma=0$, Let $\alpha=\mathrm{c}=\mathrm{k}=1$, $\mathrm{w}=0$, then:


Case 3:

Where $\sigma<0$, Let $\alpha=c=k=1, \sigma=-1$, $w=0$, then:


Where $\sigma>0$, Let $\alpha=\mathrm{c}=\mathrm{k}=\sigma=1_{s} \mathrm{w}=0$, then:


Where $\sigma=0$, Let $\alpha=\mathrm{c}=\mathrm{k}=1$, $w=0$, then:


Case 4:

Where $\sigma<0$, Let $\alpha=\mathrm{c}=\mathrm{k}=1_{s} \sigma=-1_{v} \mathrm{p}=\mathrm{q}=0.5 \& \& p \mathrm{q} \neq 1$, then:


Where $\sigma>0$, Let $a=c=k=\sigma=1, \& \& p q \neq 1$ then:


Where $\sigma=0$, Let $\alpha=c=k=1$ w $w=0, p=q=0.5, \& \& p q \neq 1$ then:


## Conclusions

In this paper, we proposed generalizing fractional sub- equation method to construct exact solutions of space-time nonlinear fractional derivative systems: Whitham-Broer-Kaup equations, Breaking Soliton equations, coupled Boussinesq-Burgers equations and coupled Burgers equations. As this method is based on the homogenous balancing principle, so it also be applied to other space-time nonlinear fractional derivative systems where the homogeneous balancing principle is satisfied. We conclude that the fractional sub-equation method is powerful, effective and convenient for nonlinear fractional PDEs.

## References:

[1] Kilbas A, Srivastava HM, Trujillo JJ. Theory and Applications of Fractional Differential Equations. North-Holland Mathematics Studies, Elsevier Science, Amsterdam, the Netherlands. 2006;204:1-523.
[2] Hilfer R. Applications of Fractional Calculus in Physics. World Scientific Publishing, River Edge, NJ, USA; 2000.
[3] West BJ, Bologna M, Grigolini P. Physics of Fractal Operators. Springer, New York, NY, USA; 2003.
[4] Miller KS, Ross B. An Introduction to the Fractional Calculus and Fractional Differential Equations.John Wiley \& Sons, New York, NY, USA; 1993.
[5] Samko SG, Kilbas AA, Marichev OI. Fractional Integrals and Derivatives. Gordon and Breach Science, Yverdon, Switzerland; 1993.
[6] Podlubny I. Fractional Differential Equations, Mathematics in Science and Engineering, Academic Press, San Diego, Calif, USA. 1999;198.
[7] Oldham KB, Spanier J. The Fractional Calculus, Academic Press, New York, NY, USA; 1974.
[8] Kiryakova V. Generalized Fractional Calculus and Applications. Pitman Research Notes in Mathematics Series, Longman Scientific \& Technical, Harlow, UK. 1994;301.
[9] Podlubny I. Fractional Differential Equations. Mathematics in Science and Engineering, Academic Press, New York, NY, USA. 1999;198.
[10] Sabatier J, Agrawal OP, Machado JAT. Advances in Fractional Calculus: Theoretical Developments and Applications in Physics and Engineering, Springer, New York, NY, USA; 2007.
[11] Mainardi F. Fractional Calculus and Waves in Linear Viscoelasticity: An Introduction to Mathematical Models, Imperial College Press, London, UK; 2010.
[12] Baleanu D, Diethelm K, Scalas E, Trujillo JJ. Fractional Calculus: Models and Numerical Methods. Series on Complexity, Nonlinearity and Chaos, World Scientific Publishing, Boston, Mass, USA. 2012;3.
[13] Yang XJ, Local Fractional Functional Analysis and Its Applications. Asian Academic Publisher, Hong Kong; 2011.
[14] Yang XJ. Advanced Local Fractional Calculus and Its Applications. World Science Publisher, New York, NY, USA; 2012.
[15] Ali AHA. The modified extended tanh-function method for solving coupled MKdV and coupled Hirota-Satsuma coupled KdV equations. Phys. Lett. A. 2007;363(5-6):420-425.
[16] Zhang S, Zhang HQ. Fractional sub-equation method and its applications to nonlinear fractional PDEs. Phys. Lett. A. 2011;375(7):1069-1073.
[17] Wang ML. Solitary wave solutions for variant Boussinesq equations. Phys. Lett. A. 1995;199(3-4):169-172.
[18] Jumarie G. Modified Riemann-Liouville derivative and fractional Taylor series of nondifferentiable functions further results. Comput. Math. Appl. 2006;51(9-10)1367-1376.
[19] Jumarie G. Fractional partial differential equations and modified Riemann-Liouville derivative new methods for solution. J. Appl. Math. Comput. 2007;24(1-2):31-48.
[20] Guo S, Mei L, Li Y, Sun Y. The improved fractional sub-equation method and its applications to the space-time fractional differential equations in fluid mechanics. Phys. Lett. A. 2012;376(4):407-411.
[21] Lu B. Bä cklund transformation of fractional Riccati equation and its applications to nonlinear fractional partial differential equations. Phys. Lett. A. 2012;376(28-29):20452048.
[22] B.Lu,(2012),Backlund Transformation of Fractional RiccatiEquation and its Applications to Nonlinear Fractional Partial Differential Equations, Phys.Lett.A,2045-2048
[23] S.M. Guo, L.Q. Mei, Y. Li, Y.F. Sun,(2012)Fractional sub-equation method and Its Application to the Space Time Fractional Deferential Equations in Fluid Mechanics, Phys. Lett. A, 376-407.
[24] Zheng B,Wen C(2013),A New Fractional Sub-Equation Method for Fractional Partial Differential Equations,WseasTransaction on Mathematics,Issue5,Volume1

