On A New Method Of Bias Reduction: Alternative To Approximately Unbiased Ratio Estimators

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#### Abstract

This paper proposes a new method of bias reduction from order $n^{-1}$ to order $n^{-2}$ resulting in a new approximately unbiased ratio estimator. The efficiency of this estimator for the ratio of population means of two characters is compared with the existing six other Ratio estimators under a linear regression model.


Keywords: Approximately Unbiased, Mean Square error, Efficiency, Regression model, Ratio Estimator,Bias,Auxiliary Variable

### 1.0 Introduction

Over the years survey samplers
Pascual(1961),Beale(1962),Tin(1965),Sahoo(1983),Sahoo(1987),Adewara(2006),Oshungade(1986), among many others have been interested in methods of improving the precision of the estimates of population parameters both at the selection and estimation stages by making use of auxiliary information. Ratio estimators are often employed by these samplers to estimating the population mean of the characteristic of interest of the population ratio.

Let $y$ and $x$ be real variates taking $y_{i}$ and $x_{i} \quad(1 \leq i \leq N)$ for $i^{\text {th }}$ unit of a population of Size $N$ with means
$\mu_{y}$ and $\mu_{x}$ respectively. Suppose that a simple random sample of size n units is drawn without replacement from the population. A commonly employed estimator in this context is traditional or classical ratio estimator $r=\frac{\bar{y}}{\bar{x}}$
where $\bar{y}$ and $\bar{x}$ denote the sample
means of $y$ and $x$ values, respectively.

### 2.0 Approximately Unbiased Ratio Type Estimators

Generally, the classical ratio estimator $(r)$ is biased; therefore, many authors
Tin(1965),Sahoo(1983),Sahoo(1987),Cochran(1977) and others have attempted to reduce this biasness in a situation where freedom from bias is important. Many authors Tin(1965),Sahoo(1983),Sahoo(1987), had also, worked on adjusting the classical ratio estimator by the term that is capable of reducing it from order $n^{-1}$ to order $\mathrm{n}^{-2}$ to attain small or moderate gain in efficiency. Several ratio type estimators which satisfy this criterion are called approximately or almost unbiased ratio type estimators.

The following approximately unbiased ratio estimators in the literature
Beale(1962), Tin(1965),Sahoo(1983),Sahoo(1987), and others are considered for comparison.

Pascual (1961) came up with the approximately unbiased ratio estimator:

$$
\begin{equation*}
\bar{Y}_{\mathrm{p}}=\bar{r}+\frac{(N-1)(\bar{y}-\bar{r} \bar{x})}{(n-1) N} \tag{2.1}
\end{equation*}
$$

This estimator has been shown to be efficient as that of combined bias ratio estimator in stratified sampling. Beale (1962) proposed another approximately unbiased estimator of order $\theta\left(n^{-2}\right)$ as

$$
\begin{equation*}
\hat{R}_{B}=\hat{R}\left(1+\theta \frac{S_{x y}}{\overline{x y}}\right) /\left(1+\theta \frac{S_{X}^{2}}{\bar{x}^{2}}\right)=\hat{R}\left(1+\theta C_{x y}\right) /\left(1+\theta C_{X}^{2}\right) \tag{2.2}
\end{equation*}
$$

Tin (1965) derived another approximately unbiased ratio estimator closely related to that of Beale (1962) which was called

Modified ratio estimator, defined as

$$
\begin{equation*}
\hat{R}_{T}=\hat{R}\left[1+\theta\left(\frac{S_{x y}}{\overline{x y}}-\frac{S_{x}^{2}}{\bar{x}^{2}}\right)\right]=\hat{R}\left(1+\theta\left(C_{X Y}-C_{X}^{2}\right)\right. \tag{2.3}
\end{equation*}
$$

, where

$$
\begin{align*}
& S_{x y}=\frac{1}{n-1} \sum_{i=1}^{n}\left(x_{i}-\bar{x}\right)\left(y_{i}-\bar{y}\right),  \tag{2.4}\\
& S_{x}^{2} / \bar{x}^{2}=C_{x}^{2}  \tag{2.5}\\
& S_{x}^{2}=\frac{1}{n-1} \sum_{i=1}^{n}\left(x_{i}-\bar{x}\right)^{2}  \tag{2.6}\\
& S_{x y} \gamma(\bar{y} \bar{x})=C_{x y} \tag{2.7}
\end{align*}
$$

And $\theta=\frac{1}{n}-\frac{1}{N}$
$\hat{R}_{\mathrm{B}}$ and $\hat{R}_{\mathrm{T}}$ have the same variance to order $0\left(n^{-2}\right)$.

Sahoo (1983) proposed another approximately unbiased ratio estimator termed almost unbiased ratio estimator, defined as

$$
\begin{equation*}
\hat{R}_{S}=\hat{R} /\left[1+\theta\left(C_{x}^{2}-C_{x y}\right)\right] \tag{2.9}
\end{equation*}
$$

It is said to be more efficient than $\hat{R}_{\mathrm{B}}$ and $\hat{R}_{\text {T. }}$

Sahoo (1987) further derived a class of almost unbiased ratio estimators, among which we have the following as its members:

$$
\begin{align*}
& \hat{R}_{s 1}=\hat{R}\left(1+\theta C_{x y}\right)\left(1-\theta C_{x}^{2}\right)  \tag{2.10}\\
& \hat{R}_{s 2}=\hat{R}\left(\frac{1-\theta C_{x}^{2}}{1-\theta C_{x y}}\right) \tag{2.11}
\end{align*}
$$

$$
\begin{equation*}
\hat{R}_{s 3}=\frac{\hat{R}}{\left[\left(1-\theta C_{x y}\right)\left(1+\theta C_{x}^{2}\right)\right]} \tag{2.12}
\end{equation*}
$$

### 3.0 The Proposed Method Of Bias Reduction: Alternative To Approximately Unbiased Ratio (AAUR) Estimators

The proposal of this estimator was based on the following standard regularity conditions:
Let $v=\left(C_{x y}, C_{x}^{2}\right)$ assume values in a bounded, closed convex subset, S , of two dimensional real spaces containing the point $V=\left(C_{x y}, C_{x}^{2}\right)$.

Let $f(v)$ be a function of $v$ (which in particular may be a polynomial in $\left(C_{x y}, C_{x}^{2}\right)$ satisfying the following conditions:
(a) The function $f(v)$ is continuous and bounded in S
(b) The first and second order partial derivatives of $f(v)$ exist and are continuous and bounded in S .
(c) After expansion under the given conditions, we get

$$
f(v)=1+\left(C_{x y}-C_{x}^{2}\right)+0\left(v-^{2}\right)
$$

Then, we have the following theorem:
Theorem: If $f(v)$ is differentiable in $C_{x y}$ and $C_{x}^{2}$ and fulfils the above regularity conditions then $\hat{R} *=\hat{R} f(v)$ is an asymptotically unbiased ratio estimator.

The unbiased ratio estimator proposed is $\hat{R}_{\mathrm{A}}=\hat{R}\left[1-\theta\left(C_{x y}+C_{x}^{2}\right)\right]$
where $\quad \mathrm{S}_{\mathrm{xy}}, \mathrm{S}^{2} \mathrm{x} / \bar{x}^{2}, \mathrm{~S}_{\mathrm{x},}^{2} \mathrm{~S}_{\mathrm{xy}} / \bar{y} \bar{x}$ and $\theta$ are as defined in equations (2.4) to (2.8)

Conventionally, $\mathrm{R}_{n}=\frac{\overline{y_{n}}}{\overline{x_{n}}}$ is taken as a biased estimate of $\mathrm{R}_{N}=\frac{\bar{y}_{N}}{\bar{x}_{N}}$, since both $\bar{y}{ }_{n}$ and $\bar{x}_{n}$ are unbiased estimates of $\bar{y}_{N}$ and $\bar{x}_{N}$ respectively.

Proof:

$$
\text { Let } \begin{align*}
R_{n}= & \overline{\overline{y_{n}}}  \tag{3.2}\\
& \Rightarrow \bar{y}_{n}=\mathrm{R}_{n} \bar{x}_{n} \tag{.3.3}
\end{align*}
$$

$R_{N}=\frac{\bar{y}_{N}}{\bar{x}_{N}}=\frac{E\left(\bar{y}_{n}\right)}{E\left(\bar{x}_{n}\right)}$
Substituting (3.3) in (3.4 ), we have
$R_{N}=\frac{E\left(R_{n} \bar{x}_{n}\right)}{E\left(\bar{x}_{n}\right)}$
Now
Bias in $R_{n}=E\left(R_{n}\right)-R_{N}$
$B\left(R_{n}\right)=E\left(R_{n}\right)-\frac{E\left(R_{n} \bar{x}_{n}\right)}{E\left(\bar{x}_{n}\right)}$
That is
$B\left(R_{n}\right)=\left\{E\left(R_{n}\right) E\left(\bar{x}_{n}\right)-R_{n} \bar{x}_{n}\right\} / E\left(\bar{x}_{n}\right)$
since the negative covariance between $R_{n}$ and $\bar{x}_{n}=E\left(R_{n}\right) E\left(\bar{x}_{n}\right)-R_{n} \bar{x}_{n \text { and }} E\left(\bar{x}_{n}\right)=\bar{x}_{N}$, then
$B\left(R_{n}\right)=-\frac{\operatorname{Cov}\left(R_{n}, \bar{x}_{n}\right)}{\bar{x}_{N}}$
Obtaining an upper bound to (3.8), we have
$\mid$ Bias in $R_{n} \left\lvert\, \leq \frac{\sigma_{R_{n}} \sigma_{\overline{X_{n}}}}{\overline{x_{n}}}=\sigma_{R_{n}} \sqrt{\frac{N-n}{N n}} C_{X}\right.$

Where $C_{x}=\frac{S_{x}}{\bar{x}_{N}}$ is the coefficient of variation of x and $\sigma_{R_{n}}$ and $\sigma_{\overline{x_{n}}}$ are the standard errors of $R_{n}$ and $x_{n}$ respectively.

From (3.10) above, we can see that if n is sufficiently large, the bias in the ratio estimate $R n$ is negligible as compared to its standard deviation.

Let $\mathrm{y}_{i}=\bar{y}_{N}+\Delta_{i}$
So that
$\overline{y_{n}}=\bar{y}_{N}+\Delta_{n}^{-}$
Where
$\mathrm{E}\left(\overline{\Delta_{n}}\right)=0$ and E $\left({\overline{\Delta^{2}}}_{n}\right)=(1-\mathrm{f}) \frac{S^{2} y}{n}$
Similarly,
Let $\quad \mathrm{x}_{i}=\overline{x_{N}}+\overline{\Delta_{i}{ }^{*}}$

So that $\overline{x_{n}}=\mathrm{x}_{N}+\bar{\Delta}_{\mathrm{ni}}{ }^{*}$
where
$\mathrm{E}\left(\overline{\Delta_{n}} *\right)=0$ and $\quad \mathrm{E}\left(\overline{\Delta_{n}} *^{2}\right)=(1-\mathrm{f}) \frac{S^{2}}{n}$

To obtain the expected value of $\mathrm{R}_{n}$, it is convenient to express it in terms of $\Delta_{\mathrm{n}}$ and $\Delta_{\mathrm{n}}{ }^{*}$ we have

$$
\begin{equation*}
\mathrm{R}_{n}=\frac{\overline{y_{N}}\left(1+\frac{\overline{\Delta_{n}}}{\overline{y_{N}}}\right)}{\overline{x_{N}}\left(1+\overline{\overline{\Delta_{n}^{*}}}\right)} \tag{3.17}
\end{equation*}
$$

It is assumed that $\overline{x_{n}} \neq 0, \quad \overline{x_{N}} \neq 0, \quad \overline{y_{N}} \neq 0$ and $\left|\overline{\overline{\Delta_{n}}}\right|<1$ so that we may expand $\left(1+\frac{\overline{x_{n}} *}{\overline{x_{N}}}\right)$ -1

Using Taylor's series expansion in powers of $\bar{\Delta}_{\mathrm{n}}{ }^{*}$, and expanding and multiplying out, we have

$$
\mathrm{R}_{n}=\mathrm{R}_{N}\left\{1+\frac{\overline{\Delta_{n}}}{\overline{y_{N}}}-\frac{\overline{\Delta^{*}}}{\overline{x_{N}}}+\frac{\overline{\Delta^{*^{2}}{ }_{n}}}{\overline{x^{2}{ }_{N}}}-\frac{\overline{\Delta_{n}}}{\overline{y_{N}}} \frac{\overline{\Delta_{n}}}{\overline{x_{N}}}+\frac{\overline{\Delta_{n}}}{\overline{y_{N}}} \overline{\frac{\Delta^{*^{2}}}{\overline{x_{N}}}}-\frac{\overline{\Delta^{*}{ }^{3}}}{n}-\frac{\overline{\Delta_{n} *^{4}}}{\overline{x^{3}{ }_{N}}}+\frac{\overline{\Delta_{n}}}{\overline{x_{N}^{4}}}-\frac{\overline{\Delta^{*}{ }_{n}}}{\overline{y_{N}}}+\ldots\right\}
$$

(3.18)

Now taking the expectation of (3.18) term by term we obtain,
$\mathrm{E}\left(R_{n}\right)=R_{N}+R_{N} . E\left\{\frac{\overline{\Delta^{*^{2}} n}}{\overline{x^{2}{ }_{N}}}-\frac{\overline{\Delta_{n}}}{\overline{y_{N}}} \frac{\overline{\Delta^{*}}{ }_{n}}{\overline{x_{N}}}+\frac{\overline{\Delta_{n}}}{\overline{y_{N}}} \frac{\overline{\Delta^{* 2}}}{\overline{x_{N}}}-\frac{\overline{\Delta^{*}{ }^{3}{ }_{n}}}{\overline{x^{3}{ }_{N}}}+\frac{\overline{\Delta^{*^{4}}}}{\overline{x^{4}{ }_{N}}}-\frac{\overline{\Delta_{n}}}{\overline{y_{N}}} \frac{\overline{\Delta^{*^{3}}{ }_{n}}}{\overline{x^{3}{ }_{N}}}+\ldots\right\} \ldots$
neglecting terms in $\overline{\Delta_{n}}$ and $\overline{\Delta_{n}}{ }^{*}$ higher than the second term i.e. $\overline{\Delta_{n}} \overline{\Delta_{n} *^{2}}, \overline{\Delta^{*}}{ }_{n}, \overline{\Delta_{n}} \overline{\Delta_{n} *^{3}}$
This approximation gives
$\mathrm{E}\left(R_{n}\right)=R_{N}+R_{N}\left[\frac{E\left(\overline{\Delta^{* 2}}{ }_{n}\right)}{\overline{x^{2}}{ }_{N}}-E \frac{\left(\overline{\Delta_{n}} \overline{\Delta_{n}}{ }^{*}\right)}{\overline{y_{N} x_{N}}}\right]$
$=R_{N}\left\{1+\frac{N-n}{N n}\left(\frac{S^{2} x}{\bar{x}_{N}{ }^{2}}-\rho \underline{\underline{y_{N}}} \frac{S_{y}}{\underline{x_{x}}}\right)\right\}$
$=R_{N}\left\{1+\frac{N-n}{N n}\left(C_{x}^{2}-\rho C x C y\right)\right\}$

Where $\mathrm{C}_{x}=\frac{S_{x}}{\overline{x_{N}}}$ and C $y_{y}=\frac{S_{y}}{\overline{y_{N}}}$
$\therefore \mathrm{E}\left[\mathrm{R}_{n}\right]=\mathrm{R}_{N}\left[1+\theta\left(\mathrm{C}_{\mathrm{x}}^{2}-\mathrm{C}_{x y}\right)\right]$
Now, following the approach of Tin (1965) in equation (2.3), by adjusting equation (3.22) for bias and by subtracting an estimate of the bias from $E\left[R_{n}\right]$,
we obtain the estimator:

$$
\begin{align*}
& \hat{R}_{\mathrm{A}}=\mathrm{E}\left[\mathrm{R}_{\mathrm{n}}\right]-2 \mathrm{R}_{\mathrm{N}} \theta \mathrm{C}_{\mathrm{x}}^{2}  \tag{3.23}\\
& \hat{R}_{\mathrm{A}}=\hat{R}\left[1+\theta\left(\mathrm{C}^{2}{ }_{\mathrm{x}}-\mathrm{C}_{x y}\right)\right]-2 \mathrm{R}_{\mathrm{N}} \theta \mathrm{C}_{\mathrm{x}}^{2} \\
& \therefore \hat{R}_{\mathrm{A}}=\hat{R}\left[1-\theta\left(\mathrm{C}_{\mathrm{XY}}+\mathrm{C}_{\mathrm{x}}^{2}\right)\right] \tag{3.24}
\end{align*}
$$

### 4.0 Derivations Of The Mean Square Error For The Alternative Unbiased Ratio Type Estimator Under The Regression Model:

$$
\begin{equation*}
\mathrm{y}_{\mathrm{i}}=\beta \mathrm{x}_{\mathrm{i}}+\mathrm{e}_{\mathrm{i}} \quad,, \mathrm{i}=1,2, \ldots, \mathrm{~N} . \tag{4.1}
\end{equation*}
$$

where $\beta$ is unknown real constant and $\mathrm{e}_{\mathrm{i}}$ 's are random variables with the following conditional expectations:

$$
\begin{align*}
& \mathrm{E}\left(\mathrm{e}_{\mathrm{i}} / \mathrm{x}_{\mathrm{i}}\right)=0  \tag{4.2}\\
& \mathrm{E}\left(\mathrm{e}_{i}^{2} / \mathrm{x}_{i}\right)=\delta \mathrm{x}_{i}^{t}, \tag{4.3}
\end{align*}
$$

With

$$
\begin{align*}
\delta & >0 \\
\mathbf{0} & \leq \mathbf{t} \quad \leq \mathbf{2} \tag{4.4}
\end{align*}
$$

and $\quad E\left(e_{i} e_{j} / x_{i} x_{j}\right)=0, i \neq j$.
It is also assumed that x has gamma distribution with parameter k as often encountered in real life survey situations.

Now, assuming (4.1), we have

$$
\begin{equation*}
\mu_{x}=\mathrm{k} ; \quad \mu_{y}=\beta \mathrm{k} ; \quad \mathrm{R}=\beta ; \quad \bar{y}=\beta \bar{x}+\bar{e} \quad \text { and } \quad \mathrm{S}_{\mathrm{xy}}=\beta \mathrm{s}_{x}^{2}+\mathrm{s}_{e x} \tag{4.5}
\end{equation*}
$$

Where

$$
\begin{equation*}
\bar{e}=\frac{\sum e_{i}}{n} ; \quad \text { and } \quad \mathrm{s}_{e x}=\frac{\sum e_{i}\left(x_{i}-x\right)}{n-1} \tag{4.6}
\end{equation*}
$$

Let $\mathrm{E}(. / \mathrm{x})$ and $\mathrm{E}_{\mathrm{x}}($.$) denote respectively the expectation operators for given \mathrm{x}$ and with respect to the distribution of $x$, so that $E()=.E_{x}(E(. / x))$ denoting the mean square error for $R_{i} \quad$ as $\operatorname{MSE}\left(R_{i}\right)$ under this model , we have

$$
\begin{equation*}
\operatorname{MSE}\left(R_{i}\right)=E\left(R_{i}-\beta\right)^{2}=E_{x}\left[E\left(R_{i}-\beta\right)^{2} \quad X_{i}\right] \quad i=1,2, \ldots, 8 \tag{4.7}
\end{equation*}
$$

Let $\mathrm{Z}_{\mathrm{i}}=x_{i}^{t}$ so that we have

$$
\begin{gather*}
\mathrm{E}(\mathrm{z})=\mathrm{Z}=\frac{\Gamma(k+t)}{\Gamma(k)}  \tag{4.8}\\
\mathrm{E}\left(\mathrm{e}_{2} / \mathrm{x} \quad\right)=\frac{\delta}{n} \bar{Z} \tag{4.9}
\end{gather*}
$$

$\mathrm{E}\left(\bar{e} \mathrm{~S}_{\mathrm{ex}} / \mathrm{x}\right)=\frac{\delta}{n} \mathrm{~S}_{\mathrm{zx}}$
and

$$
\begin{equation*}
\mathrm{E}\left(\mathrm{~S}_{e x}^{2} / \mathrm{x}\right)=\frac{\delta}{n} \mathrm{q} \tag{4.11}
\end{equation*}
$$

Where

$$
\begin{equation*}
\bar{Z}=\frac{\sum Z_{i}}{n} ; \mathrm{S}_{\mathrm{zx}}=\frac{\sum Z_{i}\left(x_{i}-\bar{x}\right)}{n-1} \text { and } \mathrm{q}=\frac{n \sum Z_{i}\left(x_{i}-\bar{x}\right)^{2}}{(n-1)^{2}} \tag{4.12}
\end{equation*}
$$

Considering (1.13) and the regression model

$$
\begin{equation*}
\bar{y}=\beta \bar{x}+\bar{e} \tag{4.13}
\end{equation*}
$$

We have

$$
\begin{equation*}
\beta=\frac{(\bar{y}-\bar{e})}{\bar{x}} \tag{4.14}
\end{equation*}
$$

and

$$
\begin{align*}
& \mathrm{S}_{\mathrm{xy}}=\beta \mathrm{s}_{x}^{2}+\mathrm{s}_{e x} \\
& \mathrm{~S}_{\mathrm{xy}}=\left[\frac{(\bar{y}-\bar{e})}{\bar{x}}\right] \mathrm{s}_{x}^{2}+\mathrm{s}_{e x} \tag{4.15}
\end{align*}
$$

Now, substituting directly into the regression model and expanding under the assumptions and approximations Tin (1965), we obtain,

$$
\begin{equation*}
\operatorname{MSE}\left(R_{i}\right)=E\left(R_{i}-\beta\right)^{2}=\operatorname{Ex}\left[E\left(R_{i}-\beta\right)^{2} / x\right] \tag{4.16}
\end{equation*}
$$

For $\mathrm{R}_{\mathrm{i}}=\hat{R}_{\mathrm{A}}$, we have,

$$
\begin{gather*}
\left(\hat{R}_{A}-\beta\right)^{2}=\left\{R\left(1-\theta\left(C_{x y}-C_{X}^{2}\right)\right)-\beta\right\}^{2}=\left\{\frac{\bar{y}}{\bar{x}}\left(1-\theta \frac{S x y}{\bar{x} y}-\theta \frac{S_{X}^{2}}{X^{2}}\right)-\left[\frac{\bar{y}}{\bar{x}}-\frac{\bar{e}}{\bar{x}}\right]\right\}^{2} \\
=\left\{\frac{\bar{y}}{\bar{x}}-\theta \frac{S x y}{\overline{x^{2}}}-\theta \bar{y} \frac{-S_{X}^{2}}{x^{3}}-\frac{\bar{y}}{\bar{x}}+\frac{\bar{e}}{\bar{x}}\right\}^{2}=\left\{\theta \frac{S x y}{\overline{\bar{x}^{2}}}-\theta \bar{y} \frac{-S_{X}^{2}}{\overline{x^{3}}}+\frac{\bar{e}}{\bar{x}}\right\}^{2} \tag{4.17}
\end{gather*}
$$

Substituting for $\mathrm{S}_{\mathrm{xy}}$, we obtain,

$$
\begin{align*}
&=\left\{\frac{\bar{e}}{\bar{x}}-\theta \frac{\bar{y}}{\overline{x^{3}}} s_{x}^{2}+\theta \frac{\bar{e}}{\overline{x^{3}}} s_{x}^{2}-\frac{\theta}{\overline{x^{2}}} s_{e x}-\theta \bar{y} \frac{S_{x}^{2}}{\overline{x^{3}}}\right\}^{2}= \\
&\left\{\begin{array}{l}
\frac{\bar{e}}{\bar{x}}+\theta \frac{\bar{e}}{\overline{x^{3}}} s_{x}^{2}-\frac{\theta}{x^{2}} \\
s_{e x}
\end{array}-2 \theta \bar{y} \frac{-S_{x}^{2}}{\overline{x^{3}}}\right\}^{2} \\
&=\left\{\frac{\bar{e}}{\bar{x}}\left[1+\theta \frac{s_{x}^{2}}{x^{2}}\right]-\frac{\theta}{\overline{x^{2}}}\left[s_{e x}+2 \bar{y} \frac{S_{x}^{2}}{\bar{x}}\right]\right\}^{2} \tag{4.18}
\end{align*}
$$

Recall as N tends to infinity, $\theta$ becomes $\frac{1}{n}$, then

$$
\begin{aligned}
& \left(\hat{R}_{A}-\beta\right)^{2}=\left\{\frac{\bar{e}}{\bar{x}}\left[1+\frac{s_{x}^{2}}{n x^{2}}\right]-\frac{1}{n \overline{x^{2}}}\left[s_{e x}+2 \bar{y} \frac{S_{x}^{2}}{\bar{x}}\right]\right\}^{2}=\left\{\frac{\bar{e}}{\bar{x}}+\frac{\bar{e}}{\overline{\overline{x^{3}}}} s_{x}^{2}-\frac{1}{n \overline{x^{2}}} s_{e x}-2 \bar{y} \frac{S_{x}^{2}}{n \overline{x^{3}}}\right\}^{2} \\
& =\frac{\overline{e^{2}}}{\overline{x^{2}}}+\overline{e^{2}} \frac{s_{x}^{2}}{n \overline{x^{4}}}-\bar{e} \frac{s_{e x}}{n \overline{x^{3}}}+\overline{e^{2}} \frac{s_{x}^{2}}{n \overline{x^{4}}}+\overline{e^{2}} \frac{\left(s_{x}^{2}\right)^{2}}{n^{2} \overline{x^{6}}}-\overline{e s_{x}^{2}} \frac{s_{e x}}{n^{2} \overline{x^{5}}}-\bar{e} \frac{s_{e x}}{n \overline{x^{3}}}-\overline{e s_{x}^{2}} \frac{s_{e x}}{n^{2} x^{5}}+\frac{s_{e x}^{2}}{n^{2} \overline{x^{4}}}+\text { terms }
\end{aligned}
$$

involving y's.

$$
\begin{align*}
& =\frac{\overline{e^{2}}}{\overline{x^{2}}}+2 \overline{e^{2}} \frac{s_{x}^{2}}{n x^{4}}-2 \bar{e} \frac{s_{e x}}{n x^{3}}+\overline{e^{2}} \frac{\left(s_{x}^{2}\right)^{2}}{n^{2} \overline{x^{6}}}-2 \overline{e s_{x}^{2}} \frac{s_{e x}}{n^{2} x^{5}}+\frac{s_{e x}^{2}}{n^{2} x^{4}}+\text { terms involving y's. } \\
& =\frac{\overline{e^{2}}}{\overline{x^{2}}}-\frac{2}{n}\left[\bar{e} \frac{s_{e x}}{\overline{x^{3}}}-\overline{e^{2}} \frac{s_{x}^{2}}{\overline{x^{4}}}\right]+\frac{1}{n^{2}}\left[\frac{s_{e x}^{2}}{\overline{x^{4}}}-2 \overline{e s_{x}^{2}} \frac{s_{e x}}{\overline{x^{5}}}+\overline{e^{2}} \frac{\left(s_{x}^{2}\right)^{2}}{\overline{x^{6}}}\right]+\text { terms involving y's } \tag{4.19}
\end{align*}
$$

Substituting the (4.9), (4.10) and (4.11) in (4.19) we obtain,

$$
\begin{equation*}
\mathrm{E}\left[\left(\left(\hat{R}_{A}-\beta\right)^{2} / \mathrm{X}\right]=\frac{\delta \bar{z}}{n \overline{x^{2}}}-\frac{2 \delta}{n^{2}}\left[\frac{s_{z x}}{\overline{x^{3}}}-\bar{z} \frac{s_{x}^{2}}{\overline{x^{4}}}\right]+\frac{\delta}{n^{3}}\left[\frac{q}{\overline{x^{4}}}-\frac{2 s_{z x}}{\overline{x^{5}}} s_{x}^{2}+\bar{z} \frac{-\left(s_{x}^{2}\right)^{2}}{\overline{x^{6}}}\right]\right. \tag{4.20}
\end{equation*}
$$

Applying the well known Taylor's series expansion method, we have,

$$
\begin{align*}
& \mathrm{E}_{x}\left(\frac{\bar{z}}{\overline{x^{2}}}\right)=\frac{Z}{k^{2}}\left(1+\frac{3}{n k}-\frac{2 t}{n k}+\frac{7}{n^{2} k^{2}}-\frac{9 t}{n^{2} k^{2}}+\frac{3 t^{2}}{n^{2} k^{2}}\right)+o\left(n^{-3}\right)  \tag{4.21}\\
& \mathrm{E}_{x}\left(\frac{s_{z x}}{\overline{x^{3}}}-\bar{z} \frac{s_{x}^{2}}{x^{4}}\right)=\frac{Z}{k^{2}}\left(-\frac{1}{k}+\frac{t}{k}-\frac{2}{n k^{2}}+\frac{6 t}{n k^{2}}-\frac{4 t^{2}}{n k^{2}}\right)+\mathrm{o}\left(\mathrm{n}^{-2}\right)  \tag{4.22}\\
& \mathrm{E}_{x}\left(\frac{q}{\overline{x^{4}}}\right)=\frac{Z}{k^{4}}\left(k+t+t^{2}\right)+o\left(n^{-1}\right)  \tag{4.23}\\
& \mathrm{E}_{x}\left(\bar{z} \frac{\left(s_{x}^{2}\right)^{2}}{x^{6}}\right)=\frac{Z}{k^{4}}+o\left(n^{-1}\right) \tag{4.24}
\end{align*}
$$

and

$$
\begin{equation*}
\mathrm{E}_{x}\left(\frac{s_{z x}}{x^{5}} s_{x}^{2}\right)=\frac{Z}{k^{4}} t+o\left(n^{-1}\right) \tag{4.25}
\end{equation*}
$$

Now, the Mean Squared Error is given by:

$$
\begin{gather*}
\mathrm{E}\left[\left(\hat{R}_{A}-\beta\right)^{2} / \mathrm{X}\right]=\frac{\delta \bar{z}}{\overline{x^{2}}}-\frac{2 \delta}{n^{2}}\left[\frac{s_{z x}}{\overline{x^{3}}}-\bar{z} \frac{s_{x}^{2}}{x^{4}}\right]+\frac{\delta}{n^{3}}\left[\frac{q}{\overline{x^{4}}}-\frac{2 s_{z x}}{\overline{x^{5}}} s_{x}^{2}+\bar{z} \frac{-\left(s_{x}^{2}\right)^{2}}{x^{6}}\right] \\
=\frac{\delta Z}{n k^{2}}\left(1+\frac{3}{n k}-\frac{2 t}{n k}+\frac{7}{n^{2} k^{2}}-\frac{9 t}{n^{2} k^{2}}+\frac{3 t^{2}}{n^{2} k^{2}}\right)-\frac{2 \delta Z}{n^{2} k^{2}}\left(-\frac{1}{k}+\frac{t}{k}-\frac{2}{n k^{2}}+\frac{6 t}{n k^{2}}-\frac{4 t^{2}}{n k^{2}}\right) \\
+\frac{\delta Z}{n^{3} k^{4}}\left(k+t+t^{2}\right) \frac{2 \delta Z t}{n^{3} k^{4}}+\frac{\delta Z}{n^{3} k^{4}}=\frac{\delta Z}{n^{3} k^{4}}\left[n^{2} k^{2}+5 n k-4 n k t+12-22 t+12 t^{2}+k\right] \tag{4.26}
\end{gather*}
$$

Thus,

$$
\begin{equation*}
\operatorname{MSE}\left(\hat{R}_{\mathrm{A}}\right)=\frac{\delta Z}{n^{3} k^{4}}\left\{n k(n k+1)+4 n k(1-t)+12\left(1+t^{2}\right)-22 t+k\right\} \tag{4.27}
\end{equation*}
$$

Similarly, the mean square errors of all the estimators are shown below:

$$
\begin{align*}
& \operatorname{MSE}\left(\hat{R}_{\mathrm{B}}\right)=\frac{\delta Z}{n^{3} k^{4}}\left\{n k(n k+1)+k+4\left(1+t^{2}\right)+2\right\}  \tag{4.28}\\
& \operatorname{MSE}\left(\hat{R}_{\mathrm{T}}\right)=\frac{\delta Z}{n^{3} k^{4}}\left\{n k(n k+1)+k+4\left(1+t^{2}\right)+2 t\right\}  \tag{4.29}\\
& \operatorname{MSE}\left(\hat{R}_{\mathrm{S}}\right)=\frac{\delta Z}{n^{3} k^{4}}\left\{n k(n k+1)+k+4\left(1+t^{2}\right)+2 t\right\}  \tag{4.30}\\
& \operatorname{MSE}\left(\hat{R}_{\mathrm{S} 1}\right)=\frac{\delta Z}{n^{3} k^{4}}\left\{n k(n k+1)+k+4\left(1+t^{2}\right)\right\}  \tag{4.31}\\
& \operatorname{MSE}\left(\hat{R}_{\mathrm{S} 2}\right)=\frac{\delta Z}{n^{3} k^{4}}\left\{n k(n k+1)+k+4\left(1+t^{2}\right)+2(2 t-1)\right\}  \tag{4.32}\\
& \operatorname{MSE}\left(\hat{R}_{\mathrm{S} 3}\right)=\frac{\delta Z}{n^{3} k^{4}}\left\{n k(n k+1)+k+4\left(1+t^{2}\right)+2(2 t+1)\right\} \tag{4.33}
\end{align*}
$$

### 5.0 Condition Under Which $\hat{R}_{\mathrm{A}}$ Is Better Than The Existing Estimators

We intend to establish the conditions under which our proposed estimator is better than the existing estimators Beale(1962), Tin(1965),Sahoo(1983),Sahoo(1987). In comparison of two estimators $e_{1}$ and $e_{2}$, when V $\left(e_{1}\right)<\operatorname{V}\left(e_{2}\right)$ or $\operatorname{MSE}\left(e_{1}\right)<\operatorname{MSE}\left(e_{2}\right)$, then, $e_{1}$ is better than $e_{2}$. Hence, in order to establish the conditions when $\hat{R}_{\mathrm{A}}$ is better than other existing estimators Pascual(1961),Beale(1962), Tin(1965),Sahoo(1983),Sahoo(1987), we compared the mean square errors of our alternative estimator with the existing ones.

Past researchers Dalabehera and Sahoo(1994), Dalabehera and Sahoo(1995) and Sahoo et al(2006) have shown that $\hat{R}_{\mathrm{S} 1}$ is better than others; therefore we compared the mean square errors of $\hat{R}_{\mathrm{A}}$ and $\hat{R}_{\text {s1 }}$.

In our comparison it was discovered that $\operatorname{MSE}\left(\hat{R}_{\mathrm{A}}\right)<\operatorname{MSE}\left(\hat{R}_{\mathrm{s} 1}\right)$ whenever, $1<\mathrm{t} \leq 2.0$ and $\mathrm{n} \mathrm{k}>8$

### 6.0 Empirical Investigations

In this section, an empirical study is carried out using a Monte Carlo technique to compare the performance of our alternative unbiased ratio estimator along side with the classical one. We shall be considering the usual model for ratio estimator $y_{i}=\beta x_{i}+e_{i}, i=1,2,3, \ldots, N$.
This work shall be viewed from the angle of real life situation which is always encountered in sampling practice by assuming that the auxiliary variable x follows a gamma (i.e. skewed population).

The approximately unbiased ratio estimators shall be compared under the following assumed model:
the regression of y on x is linear i.e, $\mathrm{y}=\alpha+\beta \mathrm{x}+\mathrm{e}$ with x having a gamma distribution with parameter $(2,1)$ ,that is, $x_{i} \sim G(2,1)$ and $e$ having a gamma distribution with parameter $(0.25,1)$, that is, $e_{i} \sim G\left(0.25 x_{i}, 1.0\right)$. Under varying values of intercept $(\alpha)=0,0.5,1.2$.
We considered the simulation of Variance, Bias, mean square error (MSE) and efficiency of the proposed alternative approximately unbiased ratio estimator $\left(\hat{R}_{\mathrm{A}}\right)$ along side with that of $\quad\left(\hat{R}_{\mathrm{s} 1}\right)$ which has been established to be the best in previous studies [9-11]

We shall consider the values $\mathrm{t}=1,1.5$. 2.0 For $\mathrm{n}=20,40,100,200$ and $\mathrm{k}=2$ under the regression model.
(i) For $\mathrm{t}=1$, we have,

$$
y_{i}=0.25 x_{i}+e_{i} ; \quad e_{i} \sim G\left(0.25 x_{i}, 1.0\right) ; \quad x_{i} \sim G(2,1) .
$$

(ii) For $\mathrm{t}=1.5$, we have,

$$
\mathrm{y}_{\mathrm{i}}=0.25 \mathrm{x}_{\mathrm{i}}+\mathrm{e}_{\mathrm{i}} \sqrt{ } \mathrm{x}_{\mathrm{i}} ; \mathrm{e}_{\mathrm{i}} \sim \mathrm{G}\left(0.25 \sqrt{\mathrm{x}_{\mathrm{i}}, 1.0}\right) ; \mathrm{x}_{\mathrm{i}} \sim \mathrm{G}(2,1) .
$$

(iii) For $\mathrm{t}=2.0$, we have,

$$
y_{i}=0.25 x_{i}+e_{i} x_{i} ; \quad e_{i} \sim G(0.25,1.0) ; \quad x_{i} \sim G(2,1) .
$$

Table 4.1: $\quad$ Simulations for $\mathbf{t}=1$

| EST | N | Variance | Bias | MSE |
| :--- | :--- | :--- | :--- | :--- |
| $\mathrm{R}_{\mathrm{S} 1}$ | 20 | 0.02229141 | 0.4957136 | 0.26802338225 |
| $\mathrm{R}_{\mathrm{A}}$ | 20 | 0.02035064 | 0.4512071 | 0.2239384870904 |
| $\mathrm{R}_{\mathrm{S} 1}$ | 40 | 0.01163586 | 0.4911259 | 0.25284050965081 |
| $\mathrm{R}_{\mathrm{A}}$ | 40 | 0.1121222 | 0.4682516 | 0.33138176090256 |
| $\mathrm{R}_{\mathrm{S} 1}$ | 100 | 0.00477786 | 0.5061191 | 0.2609344033848 |
| $\mathrm{R}_{\mathrm{A}}$ | 100 | 0.00471523 | 0.4985879 | 0.25330512402641 |
| $\mathrm{R}_{\mathrm{S} 1}$ | 200 | 0.001758906 | 0.5378979 | 0.2910930568244 |
| $\mathrm{R}_{\mathrm{A}}$ | 200 | 0.001743158 | 0.534885 | 0.287845121225 |

Table 4.2: Simulations for $\mathbf{t}=1.5$

| EST | N | Variance | Bias | MSE |
| :--- | :--- | :--- | :--- | :--- |
| $\mathrm{R}_{\mathrm{S} 1}$ | 20 | 0.05887116 | 0.5420939 | 0.35273695641721 |
| $\mathrm{R}_{\mathrm{A}}$ | 20 | 0.04969045 | 0.4892565 | 0.289070690225 |
| $\mathrm{R}_{\mathrm{S} 1}$ | 40 | 0.01163586 | 0.4911259 | 0.25284050965081 |
| $\mathrm{R}_{\mathrm{A}}$ | 40 | 0.01121222 | 0.4682516 | 0.2304717809026 |
| $\mathrm{R}_{\mathrm{S} 1}$ | 100 | 0.00477786 | 0.5061191 | 0.26093432938481 |
| $\mathrm{R}_{\mathrm{A}}$ | 100 | 0.00471523 | 0.4985879 | 0.2533051240264 |
| $\mathrm{R}_{\mathrm{S} 1}$ | 200 | 0.003271526 | 0.80595569 | 0.6528361002433761 |
| $\mathrm{R}_{\mathrm{A}}$ | 200 | 0.003247954 | 0.8021401 | 0.646676694028 |

Table 4.3: Simulations for $\mathbf{t}=\mathbf{2 . 0}$

| EST | N | Variance | Bias | MSE |
| :--- | :--- | :--- | :--- | :--- |
| $\mathrm{R}_{\mathrm{S} 1}$ | 20 | 0.01470531 | 0.3578919 | 0.14279192208561 |
| $\mathrm{R}_{\mathrm{A}}$ | 20 | 0.0151919 | 0.3350565 | 0.1274547581923 |
| $\mathrm{R}_{\mathrm{S} 1}$ | 40 | 0.00531964 | 0.3857655 | 0.15413466099025 |
| $\mathrm{R}_{\mathrm{A}}$ | 40 | 0.005348987 | 0.3753843 | 0.1462623596865 |
| $\mathrm{R}_{\mathrm{S} 1}$ | 100 | 0.002499927 | 0.3738429 | 0.14225844088041 |
| $\mathrm{R}_{\mathrm{A}}$ | 100 | 0.002493612 | 0.3699303 | 0.1393420388581 |
| $\mathrm{R}_{\mathrm{S} 1}$ | 200 | 0.0006446923 | 0.364413 | 0.133441526869 |
| $\mathrm{R}_{\mathrm{A}}$ | 200 | 0.0006427695 | 0.3626546 | 0.1321611284012 |

Conclusion: The simulations results in this study have confirmed that $\hat{R}_{\mathrm{A}}$ estimator is better than the existing ones in terms of the bias and MSE whenever $1 \leq \mathrm{t} \leq 2.0$ and $\mathrm{nk}>8$.

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