Unbalanced Two-Way Random Model with Integer-Valued Degrees of Freedom

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Abstract
The expected mean squares for unbalanced two-way random model were derived. From the ANOVA table, \( k_1 \neq k_2 \) and as such there is no obvious denominator for testing for the main effects. \( k_1 \) and \( k_2 \) are

\[
\frac{\sum n_{ij} \sum n_{ij} - N^{-1} \sum n_{ij}}{a - 1} \quad \text{and} \quad \frac{\sum n_{ij} \sum n_{ij} - N^{-1} \sum n_{ij}}{b - 1}
\]

which are the coefficients of the variance components of the interaction for factor A and factor B respectively. A theorem was proved to show that if \( k_1 = k_2 \), the unbalanced data becomes balanced and the common denominator for testing for the main effects becomes the mean square error.

Keywords: Expected mean squares, fractional degrees of freedom

1. Introduction
Unbalanced data in two-way layout are such that the numbers of observations in each cell of the layout are not the same which include cases where there are no observations in some cell. Analyzing the variance of data which are classified in two-ways with unequal numbers of observations falling into each cell of the classification needs special methods of analysis because of the inequality of the cell numbers.

Malwane and Samaradasa (1997) considered two-way ANOVA model with unequal cell frequencies without the assumption of equal error variances by taking generalized approach to finding p-values. The generalized \( F \)-test they developed in their article can be utilized in significance testing or in fixed level testing under the Neyman-Pearson theory which they claim has its advantage over the classical \( F \)-test.

Montgomery (2001) gave an easy case of analyzing unbalanced data when the classifications of the data are proportional. In this case, the number of observations in the \( ij \)th cell is

\[
n_{ij} = \frac{N_i N_j}{N}
\]

This condition implies that the numbers of observations in any two rows or columns are proportional. When this situation occurs, the standard analysis of variance can be employed with minor modification in the computing formulas for the sums of squares.

Montgomery (2001) however did not indicate if the significant testing involves fixed, random or mixed effect testing.

The two-way crossed classification with interaction for mixed model when data are unbalanced is a problem especially when deriving the expected mean squares and the variance components. When the expected mean squares for the mixed model are derived, it always contains the functions of the fixed effects. The functions of the fixed effects cannot be eliminated by considering linear combinations of the mean squares and expected mean squares. It then becomes practically impossible to determine the appropriate \( F \)-ratio for testing for the main effects.

In our paper, the expected mean squares for the random model for such lay-out were derived and appropriate \( F \)-ratio determined. The number of degrees of freedom for the denominator of the derived \( F \)-ratio is non-integer-valued. Approximating the non-integer degrees of freedom creates an uncertainty regarding the exact value of the \( F \)-ratio from the \( F \)-distribution table. If \( k_1 = k_2 \), the unbalanced data becomes balanced and the main effects can be tested using the mean square error as the common denominator for the \( F \)-ratio.
2. Methodology

Given the model

\[ y_{ijk} = \mu + \alpha_i + \beta_j + \lambda_{ij} + e_{ijk} \]

\[ \begin{align*}
  i &= 1, 2, \ldots, a \\
  j &= 1, 2, \ldots, b \\
  k &= 1, 2, \ldots, n_{ij}
\end{align*} \]  

(1)

Where

\( y_{ijk} \) is the \( k \)th observation in \( ij \)th cell,
\( \mu \) is the overall mean effect,
\( \lambda_{ij} \) is the effect of the interaction between factor A and factor B,
\( e_{ijk} \) is a random error component,
\( n_{ij} \) is the number of observation per cell; and

using the Brute-Force Method, the expected mean squares (EMS) of the parameters of Equation (1) can be shown to be

\[ \begin{align*}
  EMS_\alpha &= \sigma^2 + k_a \sigma^2_\alpha + k_\lambda \sigma^2_\lambda \\
  EMS_\beta &= \sigma^2 + k_\beta \sigma^2_\beta + k_\lambda \sigma^2_\lambda \\
  EMS_\lambda &= \sigma^2 + k_\lambda \sigma^2_\lambda \\
  EMS_e &= \sigma^2
\end{align*} \]

where

\[ \begin{align*}
  k_a &= \frac{N - N^{-1} \sum_i N_i^2}{a - 1} \\
  k_i &= \frac{\sum_j N_j \sum_i n_{ij}^2 - N^{-1} \sum_j N_j \sum_i n_{ij}^2}{a - 1} \\
  k_\beta &= \frac{b - 1}{N - N^{-1} \sum_j N_j} \\
  k_\lambda &= \frac{\sum_j N_j \sum_i n_{ij}^2 - N^{-1} \sum_i \sum_j n_{ij}^2}{b - 1} \\
  k_\lambda &= \frac{N - \sum_j N_j^2}{N^2 - \sum_j N_j^2} \frac{b - 1}{a - 1} \\
  k_\lambda &= \frac{\sum_j n_{ij}^2 N_i^{-1} N_j^{-1} \sum_j N_j - N^{-1} \sum_j n_{ij}^2}{(a - 1)(b - 1)} \\
  k_\lambda &= \frac{2 \sum_j n_{ij}^3 N_i^{-1} N_j^{-1}}{(a - 1)(b - 1)} \frac{b - 1}{a - 1}
\end{align*} \]

(2)

(3)

(4)

(5)

(6)

where

\[ \begin{align*}
  \sigma^2_\alpha &= E(\bar{y}_{..} - \bar{y}_{..})^2 = \frac{\sum_i (\bar{y}_{..} - \bar{y}_{..})^2}{n} \\
  \sigma^2_\beta &= E(\bar{y}_{..} - \bar{y}_{..})^2 = \frac{\sum_i (\bar{y}_{..} - \bar{y}_{..})^2}{n}
\end{align*} \]
\[ \sigma^2_\lambda = E(\bar{y}_{ij} - \bar{y}_{..} - \bar{y}_{.j} + \bar{y}_{..})^2 = \frac{3}{n} \sum_{ij} (\bar{y}_{ij} - \bar{y}_{..})^2 \]

\[ \sigma^2_e = E(y_{ijk} - \bar{y}_{..})^2 = \frac{\sum_{ijk} (y_{ijk} - \bar{y}_{..})^2}{n} \]

The expected mean squares (EMS) of Equation (1) are presented in the ANOVA Table shown in Table 1.

<table>
<thead>
<tr>
<th>S.V</th>
<th>d.f</th>
<th>SS</th>
<th>MS</th>
<th>EMS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Factor A</td>
<td>a-1</td>
<td>SS_A</td>
<td>MS_A</td>
<td>(\sigma^2_e + k_a \sigma^2_\alpha + k_\lambda \sigma^2_\lambda)</td>
</tr>
<tr>
<td>Factor B</td>
<td>b-1</td>
<td>SS_B</td>
<td>MS_B</td>
<td>(\sigma^2_e + k_\beta \sigma^2_\beta + k_\lambda \sigma^2_\lambda)</td>
</tr>
<tr>
<td>AxB</td>
<td>(a-1)(b-1)</td>
<td>SS_\lambda</td>
<td>MS_\lambda</td>
<td>(\sigma^2_e + k_\lambda \sigma^2_\lambda)</td>
</tr>
<tr>
<td>Error</td>
<td>N-pq</td>
<td>SS_e</td>
<td>SS_e</td>
<td>(\sigma^2_e)</td>
</tr>
<tr>
<td>Total</td>
<td>N-1</td>
<td>SS_T</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Table 1: ANOVA Table for Unbalanced data.

From the expected mean squares in Table 1, we can see that the appropriate statistic for testing the no interaction hypothesis \(H_0: \sigma^2_\lambda = 0\) is

\[ F_e = \frac{MS_\lambda}{MS_e} \]

This is because, under \(H_0\) both numerator and denominator of \(F_e\) have expectation \(\sigma^2_e\).

The case is different when testing for \(H_0: \sigma^2_\alpha = 0\) because the numerator expectation is \(\sigma^2_e + k_1 \sigma^2_\lambda\) and no other expectation in Table 1 that is \(\sigma^2_e + k_1 \sigma^2_\lambda\) under \(H_0\).

The case is the same when testing for \(H_0: \sigma^2_\beta = 0\) if we are interested in testing for the main effects A and B using \(F\) -test Statistic, there would be no obvious denominator for testing the hypotheses \(H_0: \sigma^2_\alpha = 0\) and \(H_0: \sigma^2_\beta = 0\) because \(k_1 \neq k_2\).

If we are interested in testing \(H_0: \sigma^2_\alpha = 0\) and we can find a linear combination of independent mean squares with expectation:

\[ MS_\phi = \sigma^2_e + k_1 \sigma^2_\lambda \]  \(\text{(7)}\)

we would have \(F\) -test for the null hypothesis given by

\[ F_{f_a, f_\phi} = \frac{MS_e}{MS_\phi} \]

\(f_a\) and \(f_\phi\) are the degrees of freedom for the numerator and denominator of the \(F\) -ratio respectively.
\( MS\phi \) is obtained from Table 1 as follows:

\[
\sigma^2_e = MS_e
\]

\[
MS_\lambda = \sigma^2_e + k_3 \sigma^2_\lambda
\]

Thus

\[
MS_\lambda = MS_e + k_3 \sigma^2_\lambda
\]

This implies

\[
\sigma^2_\lambda = \frac{MS_\lambda - MS_e}{k_3}
\]

Substituting Equation (8) in Equation (7) gives

\[
MS\phi = \left[ MS_e + k_1 \left( \frac{MS_\lambda - MS_e}{k_3} \right) \right]
\]

\[
= MS_e + \left( \frac{k_1}{k_3} \right) MS_\lambda - \left( \frac{k_1}{k_3} \right) MS_e
\]

Therefore

\[
MS\phi = (1 - \theta_1) MS_e + (\theta_1) MS_\lambda
\]

where

\[
\theta_1 = \frac{k_1}{k_3}
\]

From Castrup (2010) the degree of freedom for the denominator is:

\[
f_{\phi} = \frac{(MS\phi)^2}{(1 - \theta_1)^2 MS_e^2 + (\theta_1)^2 MS_\lambda^2}
\]

Similarly, testing \( H_0 : \sigma^2_\beta = 0 \)

\[
MS\phi = (1 - \theta_2) MS_e + (\theta_2) MS_\lambda
\]

Similarly from Castrup (2010), the degree of freedom for the denominator is

\[
f_{\phi} = \frac{(MS\phi)^2}{(1 - \theta_2)^2 MS_e^2 + (\theta_2)^2 MS_\lambda^2}
\]

\[
\theta_2 = \frac{k_2}{k_3}
\]

where \( f_e \) and \( f_\lambda \) are the degree of freedom obtained from the ANOVA Table 1

The sums of squares for the unbalanced data which are analogous to balanced designs are:

\[
SS_A = \sum_i N_i \left( \bar{y}_{i.} - \bar{y}_{..} \right)^2
\]

\[
SS_B = \sum_j N_j \left( \bar{y}_{.j} - \bar{y}_{..} \right)^2
\]
\[ SS_\lambda = \sum_y n_y (\bar{y}_{.,-} - \bar{y}_{., y} + \bar{y}_{.,.})^2 \]  
\[ SS_e = \sum_{yik} (y_{yik} - \bar{y}_{y.})^2 \]  

Equations (10) and (11) are non-integer-valued degrees of freedom. This means we need to correct to the nearest whole number before reading the value from our \( F \)-distribution table. However, if \( k_1 = k_2 \), the problem of fractional degrees of freedom will be solved.

**Theorem:**

Given \( H_0 : \sigma_{a}^2 = 0 \), and \( H_0 : \sigma_{\beta}^2 = 0 \), then \( F = \frac{MS_a}{MS_e} = \frac{MS_\beta}{MS_e} \) if and only if \( k_1 = k_2 \).

**Proof:**

From Table 1

\[ MS_a = \sigma^2 + k_a \sigma_a^2 + k_1 \sigma_\lambda^2 \]
\[ MS_\beta = \sigma^2 + k_\beta \sigma_\beta^2 + k_2 \sigma_\lambda^2 \]

and

\[ MS_e = \sigma^2 \]

Thus

\[ MS_a = \sigma^2 + k_a \sigma_a^2 + k_1 \sigma_\lambda^2 \]

and

\[ MS_\beta = \sigma^2 + k_\beta \sigma_\beta^2 + k_2 \sigma_\lambda^2 \]

This implies that

\[ \frac{MS_a}{MS_e} = 1 + \frac{k_a \sigma_a^2 + k_1 \sigma_\lambda^2}{MS_e} \quad \text{and} \quad \frac{MS_\beta}{MS_e} = 1 + \frac{k_\beta \sigma_\beta^2 + k_2 \sigma_\lambda^2}{MS_e} \]  

(16)

Now, suppose \( k_1 = k_2 \), then we obtain from Equation (16)

\[ \frac{MS_a}{MS_e} - \frac{MS_\beta}{MS_e} = \frac{k_a \sigma_a^2 - k_\beta \sigma_\beta^2}{MS_e} \]  

(17)

Thus, testing that \( \sigma_{a}^2 = \sigma_{\beta}^2 = 0 \), we obtain from Equation (17), that

\[ \frac{MS_a}{MS_e} = \frac{MS_\beta}{MS_e} \]

Conversely, suppose
That is, suppose

\[ \sigma_e^2 + k_a \sigma_e^2 + k_\beta \sigma_e^2 = \sigma_e^2 + k_\beta \sigma_e^2 + k_\lambda \sigma_e^2 \]

then, testing that \( \sigma_a^2 = \sigma_\beta^2 = 0 \) gives

\[ k_\alpha \sigma_e^2 = k_\lambda \sigma_e^2 \]

This implies that \( (k_\lambda - k_\lambda) \sigma_e^2 = 0 \)
but since \( \sigma_e^2 \neq 0 \), then \( k_\lambda - k_\lambda = 0 \), that is \( k_\lambda = k_\lambda \).
This completes the proof.

3. Estimation of missing values

There are several methods of estimating missing values in unbalanced data. Howell (2008) gave some methods of treating missing data. Some of the methods are Mean substitution, Regression substitution, Listwise deletion and Pair-wise deletion.

Little and Rubin (2002) gave some classifications of missingness. We have

(a) Missingness at random (MCAR): This is a situation where the probability of missing data does not depend on observed or unobserved data.

(b) Missing at random (MAR): Here the probability of missing data does not depend on the unobserved data but conditional on the observed data.

(c) Missing not at random (MNAR): Here the probability of missing data does depend on the unobserved, conditional on the observed data.

Irrespective of the classifications, our interest is to estimate missing value(s) to set \( \lambda_1 = \lambda_2 \) using any appropriate method of estimation. Each estimation will lead to subtracting one from the error mean square. See Montgomery (2001).

4. Illustrative example

Suppose an oil company gets its crude oil from 3 different sources and refines it in 3 different refineries. In one part of the refining process, a measurement of efficiency is taken as a percentage and recorded as an integer between 0 and 100. The data are shown below:

<table>
<thead>
<tr>
<th>Refinery</th>
<th>Texas</th>
<th>Oklahoma</th>
<th>Gulf of Mexico</th>
</tr>
</thead>
<tbody>
<tr>
<td>Galveston</td>
<td>31</td>
<td>36,38</td>
<td>26</td>
</tr>
<tr>
<td>Newark</td>
<td>39,59</td>
<td>37,36</td>
<td>42</td>
</tr>
<tr>
<td>Savanna</td>
<td>42,44</td>
<td>36,42</td>
<td>26,37</td>
</tr>
</tbody>
</table>

Table 2: Crude oil data from Searle (1997), p.162

The model is of the type in Equation (1), where,

\[ y_{ijk} \] is the measurement of the efficiency,
\[ \mu \] is the overall mean,
\[ \alpha_j \] is the average effects of the refineries,
\[ \beta_j \] is the average effects of the sources of the crude oil,
\[ \lambda_{ij} \] is the interaction between the refineries and the sources of the crude oil and
\[ e_{ijk} \] is the error associated with \( y_{ijk} \).
From Equations (3) and (5)
\[ k_1 = k_2 = 1.75 \]
and from Equation (6)
\[ k_3 = 1.6 \]
Using Equations (12), (13), (14) and (15), the mean sums of squares for factor A, factor B, the interaction between factor A and B and the error term has been calculated and presented below.

\[ MS_a = 108.08; \ MS_\beta = 118.34; \ MS_\lambda = 31.52 \text{ and } MS_e = 47.17. \]

Since \( k_1 = k_2 \), and \( \theta_1 = \theta_2 = 1.09 \)

This implies that \( MS_{\phi_1} = MS_{\phi_2} \)

From the above Theorem, our hypotheses shall be:

\[ H_{10} : \sigma^2_{\alpha} = 0 \text{ versus the alternative, } H_{11} : \text{ at least one of the variances differ.} \]

Thus
\[ F = \frac{MS_{\alpha}}{MS_e} = \frac{108.08}{47.17} = 2.29 \]

From the F-distribution table, we have \( F_{2,6}^{0.05} = 5.14 \). Since 2.29 < 5.14 the variances are non-significant.

Similarly, \( H_{02} : \sigma^2_{\beta} = 0 \text{ versus the alternative, } H_{12} : \text{ at least one of the variances differ.} \)

\[ F = \frac{MS_{\beta}}{MS_e} = \frac{118.34}{47.17} = 2.51 \]

From the F-distribution table, we have \( F_{2,6}^{0.05} = 5.14 \) and since 2.51 < 5.14 the variances are also non-significant.

Finally, for \( H_{03} : \sigma^2_{\lambda} = 0 \text{ versus the alternative, } H_{13} : \text{ at least one differs,} \)

\[ F = \frac{MS_{\lambda}}{MS_e} = \frac{31.52}{47.17} = 0.67 \]

From the F-distribution table, we have \( F_{4,6}^{0.05} = 4.53 \), and since 0.67 < 4.53 the variances are non-significant.

5. Summary and Conclusion

We have seen that when \( k_1 \neq k_2 \), there are no obvious denominator for testing for the main effects in an unbalanced two-way random model. This is as a result of the presence of interaction. From our theorem, when \( k_1 = k_2 \), the interaction is removed from the data and the main effects can then be tested using \( MS_e \) as the denominator of our F-test which has an integer-valued degree of freedom.

In a situation where \( k_1 \neq k_2 \), the missing values should be estimated to set \( k_1 = k_2 \) so as to avoid testing for the main effects when interaction is present.

For valid results, it is generally advisable to test for the main effects in an unbalanced two-way random model when interaction is absent.
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