

Reduction of Switching Losses in VSC Using DC Link Fuzzy Logic Controller

V.Manoj^{*} K.Manohar, B.Durga Prasad

Department of Electrical and Electronics Engineering, Gitam University, Visakhapatnam 530045, Andhra Pradesh, India

* jonam287@gmail.com

Abstract

The main objective of a soft switching circuit is to reduce the switching losses in a static converter when is switched at high frequency. In this paper a DC link fuzzy logic controller applied to a VSC (voltage source converter). The lossless switching is tested in a parallel VSC and is verified the effect of the soft switching circuit in MATLAB-SIMULINK. During the switching interval some power is dissipated in power transistors. A VSC in parallel to the DC link is added in simulation to show the instantaneous power in any switch.

Keywords: fuzzy logic controller with rule-viewer, dc link, soft switching, voltage source inverter, lossless switching

1. Introduction

Resonant DC link inverters allow soft switching of semiconductor power devices. Soft switching provides an effective means of reducing device stress and switching losses. The term soft switching means the devices are switched only when the voltage across the device and/or current through the device is zero resulting in zero voltage switching (ZVS) or zero current switching (ZCS). The most common soft switching circuits use a LC resonant tank to link the power supply to the switching circuit. Normally the resonant circuit oscillates between zero and twice the supply voltage and ZVS occurs when the link voltage is zero. The switching losses limit the useable switching frequency. For this reason, the reduction of switching losses with resonant or soft switching topologies is necessary. PWM Inverter is an important circuit in Power Electronics and Drives System. Its application includes induction motor drives, AC power supplies and actuation system. For higher output power, typically greater 2kVA, three phase system will be more appropriate. The main use of fuzzy control system is based on empirical rules is more effective. Fuzzy control can be used to improve existing traditional control systems by adding a layer of intelligence to the current control method. The new HVDC system based on the voltage source converters (VSCs) and pulse width modulation (PWM) known as VSC - HVDC shown in figure 1.VSC-HVDC has many advantages compared with the traditional HVDC one advantage is possible support of weak AC systems or even passive systems without phase change voltage.

2. DC Link Model

This model consists of IGBT's, Capacitor and Inductor. The circuit is connected in between supply and VSC to make DC link voltage zero when converter changes its stages. The link consists of three controllable switches and diodes D1,D2,D3. Here Lr and Cr are the resonant components. The voltage (VCr) and current. (ICr) are the corresponding signals in the capacitor which is given to the fuzzy controller as input..

3. Fuzzy Logic Control

The fuzzy logic controller consists of Fuzzy Inference System Editor. The simulation of soft switching circuit is developed in this FIS editor. VCr and ICr are the inputs of the fuzzy controller. The output of the controller is crisp value. This Graphical User Interface consists of FIS Editor, Membership function Editor, Rule Editor, Rule Viewer and Surface Viewer.



4. Soft Switching Scheme Simulink

The soft switching scheme consists of a DC link block and fuzzy controller with Rule Viewer. The output of the DC link VCr and ICr signals are given to the fuzzy controller which generates the activation order of switches in the resonant block. The output of the DC link are showed in figure 10. The crisp output is given to the matlab embedded function block. It generates the timing signals T1,T2,T3 to the IGBT switches in the DC link block.

5. Soft Switching Verification

For the soft switching the fuzzy DC link structure is added to the full bridge converter (AC-DC) in order to reduce the power losses in any switch of the converter. During switching interval some power is dissipated in transistors. In order to reduce this effect, VSC in parallel to the DC link is added to show the instantaneous power in any switch. The VSC is the chosen circuit because it is widely used in all kinds of applications due to its controllability, compact modular design, eases of system interface and low environmental impact. The VSC is the basic part in an electric drive; this is synthesized with SPWM signals gating the IGBT full bridge, generating a three phase AC signal. The VSC is nested in a subsystem with a three phase measurement and an induction as load, the PWM signals are generated depending of the modulation index and frequency, the carrier frequency is 2 kHz. The Power dissipation waveform obtained uses a simulation time of 0.02s. As previously stated, the diagram block depicted in figure 14 is now realized in Simulink with the same parallel VSC with the current and voltage measurement block, figure 14shows the connection. Figure 15 shows the reduction of inner power with the area under curve integration. The load is not affected because it is highly inductive.

6. Conclusion

The fuzzy logic control is a good solution in non-linear and complicated decision systems like those exposed here, in order to enable the multiple operation ranges and the changes in current of the VSC. The proposed fuzzy logic controller provides robust and reliable control of the DC Link. The design methodologies of the controller and simulation results are presented in this paper. The objective is make voltage zero whenever inverter switches change statesConsiderable reduction of power in the proposed circuit of the parallel Voltage Source Converter.

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V.Manoj born in the year 1988 is currently doing his Post Graduate course in Power systems and automation in Electrical and Electronics Engineering, department of GITAM Institute of Technology, GITAM University, Visakhapatnam, India, Bachelor degree in Electrical and Electronics Engineering from JNTU Kakinada, Andhra Pradesh, India, in 2010.

K.Manohar received his master degree in Power system control and automation from JNTU Hyderabad, in 2008, Bachelor degree in Electrical Engineering from JNTU Hyderabad, India, in 2005. He is currently working as an Assistant Professor of Electrical and Electronics Engineering department at GITAM Institute of Technology, GITAM University, Visakhapatnam, Andhra Pradesh, India. His research interest includes Power system protection HVDC transmission.

B.Durga Prasad received his master degree in Power system control and automation from Andhra University, in 2008, Bachelor degree in Electrical Engineering from JNTU Hyderabad, India, in 2004. He is currently working as an Assistant Professor of Electrical and Electronics Engineering department at GITAM Institute of Technology, GITAM University, Visakhapatnam, Andhra Pradesh, India.



Figure 3. Fuzzy Inference System Editor

Voltage-Inpu



Figure 3 depicts that the Fuzzy Inference System Editor consists of two input variables i.e., Current, Voltage and one Output variable.



Here the Membership Functions characterizing the current, voltage inputs and output with linguistic variables.

Current input ranges from [-20 30], Voltage input ranges from [-100 600] and Output ranges from [-20 20].





Figure 7. Rule view of input membership functions

The rule viewer displays the fuzzy inference process according to rule editor and fuzzy editor. The three small plots across the top of the figure represent the antecedent and consequent of the first rule.



Figure 8. Surface view of input membership functions





Figure 9. Fuzzy DC Link structure in simulink



Figure 10. Waveforms Simu Time /itching Scheme



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Figure 12. Without soft switching circuit

Figure 12 depicts that the VSC is nested in a subsystem with a three phase measurement and an induction as load, the PWM signals are generated depending of the modulation index and frequency, the carrier frequency is 2 kHz.





Figure 13. IGBT Power d it soft switching circuit Figure 13 depicts that the power dissipated in the without soft switching circuit is 117 Watts.



Figure 14. System with fuzzy DC link controller (Fuzzy DC link controller is added in parallel with inverter).



Figure 15. IGBT Power Time

switching circuit

Figure 15 depicts that the power dissipated in the son swncning circuit is 14 Watts and switching loss is less when compared to without fuzzy controller which has 117 Watts.



| Vc/Ic | Ν | Z | PS | PL |
|-------|----|----|----|----|
| N | NL | NL | PM | РМ |
| Z | NL | PS | PS | NM |
| PS | PL | PL | NS | NM |
| PL | PL | PL | NS | NS |

Table 1. Fuzzy rule base decision table

The decision table of control rule base determine what switch must turn off or on, due to the current and voltage changes. The above table consists of 16 rules. The rules can be written as follows:

1.If Ic is N and Vc is N THEN OUTPUT is NL 2.If Ic is N and Vc is Z THEN OUTPUT is NL 3.If Icis N and Vc is PS THEN OUTPUT is PL This academic article was published by The International Institute for Science, Technology and Education (IISTE). The IISTE is a pioneer in the Open Access Publishing service based in the U.S. and Europe. The aim of the institute is Accelerating Global Knowledge Sharing.

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