# $\Gamma^{*}-$ derivation and Jordan $\Gamma^{*}-$ derivation on Prime $\Gamma$-ring with Involution 

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#### Abstract

Let $M$ be a 2 -torsion free prime $\Gamma$-ring with involution satisfying the condition that $a \alpha b \beta c=a \beta b \alpha c(a, b, c \in M$ and $\alpha, \beta \in \Gamma)$. In this paper we will give the relation between $\Gamma^{*}$-derivation and Jordan $\Gamma^{*}$-derivation. Also we will prove that if $d$ is a non-zero Jordan $\Gamma^{*}$-derivation such that $d(x \alpha y)=d(y \alpha x)$ for all $x, y \in M$ and $\alpha \in \Gamma$, then $M$ is a commutative $\Gamma$-ring with involution.


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## 1 Introduction

The notion of $\Gamma$-rings was first introduced by Nobusawa [14] who also showed that $\Gamma$-rings are more general than rings. Bernes[17] slightly weakened the conditions in the definition of $\Gamma$-ring in the sense of Nobusawa. Bernes[17], Kyuno[16], Luh[5], Ceven[18], Hoque and Paul[8, 10, 11] and others established a large number of important basic properties on $\Gamma$-rings in various ways and determined some more remarkable results of $\Gamma$-rings. We start with some definitions. Let $M$ and $\Gamma$ be additive abelian groups. If there exists a mapping $M \times \Gamma \times M \longrightarrow M$ defined by $(x, \alpha, y) \longrightarrow(x \alpha y)$ which satisfies the conditions
(i) $x \alpha y \in M$.
(ii) $(x+y) \alpha z=x \alpha z+y \alpha z, x(\alpha+\beta) y=x \alpha y+x \beta y, x \alpha(y+z)=x \alpha y+x \alpha z$.
(iii) $(x \alpha y) \beta z=x \alpha(y \beta z)$
then $M$ is called a $\Gamma$-ring (see $[5],[9])$. Let $M$ be a $\Gamma$-ring. Then an additive subgroup $U$ of $M$ is called a left (right) ideal of $M$ if $M \Gamma U \subset U(U \Gamma M \subset U)$. If $U$ is both a left and a right ideal, then we say $U$ is an ideal of $M$. Suppose again that $M$ is a $\Gamma$-ring. Then $M$ is said to be 2-torsion free if $2 x=0$ implies $x=0$ for all $x \in M$. An ideal $P_{1}$ of a $\Gamma$-ring $M$ is said to be prime if for some ideals $A$ and $B$ of $M, A \Gamma B \subseteq P_{1}$ implies $A \subseteq P_{1}$ or $B \subseteq P_{1}$. An ideal $P_{2}$ of a $\Gamma$-ring $M$ is said to be semiprime if for any ideal $U$ of $M, U \Gamma U \subseteq P_{2}$ implies $U \subseteq P_{2}$. A $\Gamma$-ring $M$ is said to be prime if $a \Gamma M \Gamma b=(0)$ with $a, b \in M$, implies $a=0$ or $b=0$ and semiprime if $a \Gamma M \Gamma a=(0)$ with $a \in M$ implies $a=0$. Furthermore, $M$ is said to be a commutative $\Gamma$-ring if $x \alpha y=y \alpha x$ for all $x, y \in M$ and $\alpha \in \Gamma$. The set $\mathrm{Z}(\mathrm{M})=\{x \in M: x \alpha y=y \alpha x$ for all $\alpha \in \Gamma, y \in M\}$ is called the center of the $\Gamma$-ring $M$. If $M$ is a $\Gamma$-ring, then $[x, y]_{\alpha}=x \alpha y-y \alpha x$ is known as the commutator of $x$ and $y$ with respect to $\alpha$, where $x, y \in M$ and $\alpha \in \Gamma$. We make the following basic commutator identities:

$$
\begin{align*}
& {[x \alpha y, z]_{\beta}=[x, z]_{\beta} \alpha y+x[\alpha, \beta]_{z} y+x \alpha[y, z]_{\beta}}  \tag{1}\\
& {[x, y \alpha z]_{\beta}=[x, y]_{\beta} \alpha z+y[\alpha, \beta]_{x} z+y \alpha[x, z]_{\beta}} \tag{2}
\end{align*}
$$

for all $x, y, z \in M$ and $\alpha, \beta \in \Gamma$. Now, we consider the following assumption:
(A) $x \alpha y \beta z=x \beta y \alpha z$ for all $x, y, z \in M$ and $\alpha, \beta \in \Gamma$.

According to assumption (A), the above commutator identities reduce to $[x \alpha y, z]_{\beta}=[x, z]_{\beta} \alpha y+x \alpha[y, z]_{\beta}$ and $[x, y \alpha z]_{\beta}=[x, y]_{\beta} \alpha z+y \alpha[x, z]_{\beta}$. which we will extensively used.

Bernes[17], Luh[5], Kyuno[16], Hoque and Paul[10] studied the structure of $\Gamma$-rings and obtained various generalizations of corresponding parts in ring theory. Note that during the last few decades many authors have studied derivations in the context of prime and semiprime rings and $\Gamma$-rings with involution ([6],[7],[12],[15],[4]). The notion of derivation and Jordan derivation on a $\Gamma$-ring were defined by Sapanci and Nakajima[13].

Definition 1.1. [18] An additive mapping $D: M \longrightarrow M$ is called a derivation if $D(x \alpha y)=D(x) \alpha y+x \alpha D(y))$, which holds for all $x, y \in M$ and $\alpha \in \Gamma$.

Definition 1.2. [18] An additive mapping $D: M \longrightarrow M$ is called a Jordan derivation if $D(x \alpha x)=D(x) \alpha x+x \alpha D(x))$, which holds for all $x \in M$ and $\alpha \in \Gamma$.

Definition 1.3. [18] $A$-ring $M$ is called a completely prime if $a \Gamma b=0$ implies that $a=0$ or $b=0$, where $a, b \in M$

Remark 1. [18] Every completely prime $\Gamma$-ring is prime.
Definition 1.4. An additive mapping $(x \alpha x) \rightarrow(x \alpha x)^{*}$ on a $\Gamma$-ring $M$ is called an involution if $(x \alpha y)^{*}=y^{*} \alpha x^{*}$ and $(x \alpha x)^{* *}=x \alpha x$ for all $x, y \in M$ and $\alpha \in \Gamma$. A $\Gamma$-ring $M$ equipped with an involution is called a $\Gamma$-ring $M$ with involution (also known as $\Gamma^{*}$-ring).

Definition 1.5. An additive mapping $d: M \longrightarrow M$ is called $\Gamma^{*}$-derivation if $d(x \alpha y)=$ $d(x) \alpha y^{*}+x \alpha d(y)$ which holds for all $x, y \in M$ and $\alpha \in \Gamma$.

Definition 1.6. An additive mapping $d: M \longrightarrow M$ is called a Jordan $\Gamma^{*}-$ derivation if $d(x \alpha x)=d(x) \alpha x^{*}+x \alpha d(x)$ which holds for all $x \in M$ and $\alpha \in \Gamma$.

Example 1 Let R be a commutative ring with $\operatorname{chR}=2$. Define $M=$ $\left\{\left[\begin{array}{ll}a & b \\ 0 & a\end{array}\right]: a, b \in R\right\}$ and $\Gamma=\left\{\left[\begin{array}{cc}\alpha & 0 \\ 0 & \alpha\end{array}\right]: \alpha \in R\right\}$, then $M$ is a $\Gamma$-ring under addition and multiplication of matrices.
Define a mapping $d: M \rightarrow M$ by $d\left(\left[\begin{array}{ll}a & b \\ 0 & a\end{array}\right]\right)=\left[\begin{array}{ll}0 & b \\ 0 & 0\end{array}\right]$
To show that $d$ is a $\Gamma^{*}$-derivation, let
$x=\left[\begin{array}{ll}a & b \\ 0 & a\end{array}\right], y=\left[\begin{array}{ll}c & d \\ 0 & c\end{array}\right], y^{*}=\left[\begin{array}{cc}-c & d \\ 0 & -c\end{array}\right]$,
then $d(x \alpha y)=d(x) \alpha y^{*}+x \alpha d(y)$. Hence, $d$ is a $\Gamma^{*}$-derivation
It is clear that every $\Gamma^{*}$-derivation is a Jordan $\Gamma^{*}$-derivation, but the converse in general is not true.

Example 2 Let $M$ be a $\Gamma$-ring and let $a \in M$ such that $a \Gamma a=(0)$ and $x \alpha a \beta x=0$ for all $x \in M$ and $\alpha, \beta \in \Gamma$, but $x \alpha a \beta y \neq 0$ for some $x, y \in M$ such that $x \neq y$.
Define a map $d: M \rightarrow M$ by $d(x)=x \alpha a+a \alpha x^{*}$ for all $x \in M$ and $\alpha \in \Gamma$, then $d$ is a Jordan $\Gamma^{*}$-derivation but not $\Gamma^{*}$-derivation.

In this paper we will give the relation between $\Gamma^{*}$ - derivation and Jordan $\Gamma^{*}$-derivation. Also we will prove that if $d$ is a non-zero Jordan $\Gamma^{*}$-derivation such that $d(x \alpha y)=d(y \alpha x)$ for all $x, y \in M$ and $\alpha \in \Gamma$, then $M$ is a commutative $\Gamma$-ring with involution.

## $2 \Gamma^{*}$-derivation and Jordan $\Gamma^{*}$-derivation

To prove our main results, we need the following lemmas.
Lemma 2.1. Let $M$ be a non-commutative prime $\Gamma$-ring with involution satisfying assumption $A$, let $d: M \rightarrow M$ be $a \Gamma^{*}$-derivation, then $d=0$.
Proof. We have

$$
\begin{equation*}
d(x \alpha y)=d(x) \alpha y^{*}+x \alpha d(y) \tag{3}
\end{equation*}
$$

for all $x, y \in M$ and $\alpha \in \Gamma$. Replacing $y$ by $y \beta z$ in (3) we get

$$
\begin{equation*}
d(x \alpha(y \beta z))=d(x) \alpha z^{*} \beta y^{*}+x \alpha d(y) \beta z^{*}+x \alpha y \beta d(z) \tag{4}
\end{equation*}
$$

for all $x, y \in M$ and $\alpha, \beta \in \Gamma$ and

$$
\begin{equation*}
d((x \alpha y) \beta z))=d(x) \alpha y^{*} \beta z^{*}+x \alpha d(y) \beta z^{*}+x \alpha y \beta d(z) \tag{5}
\end{equation*}
$$

for all $x, y, z \in M$ and $\alpha, \beta \in \Gamma$. By compare (4) and (5), we get

$$
\begin{equation*}
d(x) \alpha\left[z^{*}, y^{*}\right]_{\beta}=0 \tag{6}
\end{equation*}
$$

for all $x, y, z \in M$ and $\alpha, \beta \in \Gamma$, then by using [3], we get $d=0$.

Lemma 2.2. Let $M$ be a semiprime $\Gamma$-ring satisfying assumption $A$, and suppose that $a \in M$ centralizes all $[x, y]_{\alpha}$ for all $x, y \in M$ and $\alpha \in \Gamma$. Then $a \in Z(M)$.

Proof. The proof of this lemma can be found in [3] (Lemma 2.4).
Lemma 2.3. Let $M$ be a 2-torsion free non-commutative prime $\Gamma$-ring with involution satisfying assumption ( $A$ ) and suppose there exists an element $a \in M$ such that $a \alpha[x, y]_{\beta}^{*}=$ $[x, y]_{\beta} \alpha a$ for all $x, y \in M$ and $\alpha, \beta \in \Gamma$, then $a=0$.

## Proof. We have

$$
\begin{equation*}
a \alpha[x, y]_{\beta}^{*}=[x, y]_{\beta} \alpha a \tag{7}
\end{equation*}
$$

for all $x, y \in M$ and $\alpha, \beta \in \Gamma$. Replace $y$ by $x \delta y$ in (7)

$$
\begin{aligned}
a \alpha[x, x \delta y]_{\beta}^{*} & =[x, x \delta y]_{\beta} \alpha a \\
a \alpha\left(y^{*} \delta[x, x]_{\beta}^{*}+[x, y]_{\beta}^{*} \delta x^{*}\right) & =\left(x \delta[x, y]_{\beta}+[x, x]_{\beta} \delta y\right) \alpha a
\end{aligned}
$$

for all $x, y \in M$ and $\alpha, \beta, \delta \in \Gamma$, then after reduces, we obtain

$$
\begin{equation*}
a \alpha[x, y]_{\beta}^{*} \delta x^{*}=x \delta[x, y]_{\beta} \alpha a \tag{8}
\end{equation*}
$$

for all $x, y \in M$ and $\alpha, \beta, \delta \in M$. By using relation (7), (8), we get

$$
\begin{aligned}
& {[x, y]_{\beta} \alpha a \delta x^{*}=x \delta[x, y]_{\beta} \alpha a} \\
& {[x, y]_{\beta} \alpha x \delta a=x \delta[x, y]_{\beta} \alpha a} \\
& {[x, y]_{\beta} \alpha x \delta a-x \delta[x, y]_{\beta} \alpha a=0}
\end{aligned}
$$

The substitution $z=\left[z_{1}, z_{2}\right]_{\gamma}$ where $z_{1}, z_{2} \in M$ for $x$ in above relation

$$
[z, y]_{\beta} \alpha z \delta a-z \delta[z, y]_{\beta} \alpha a=0
$$

gives

$$
\begin{equation*}
\left[[z, y]_{\beta}, z\right]_{\delta} \alpha a=0 \tag{9}
\end{equation*}
$$

for all $z, y \in M$ and $\alpha, \beta, \delta \in \Gamma$. Putting $y \gamma w$ for $y$ in (9)

$$
\begin{aligned}
& {\left[[z, y \gamma w]_{\beta}, z\right]_{\delta} \alpha a=0} \\
& {\left[y \gamma[z, w]_{\beta}+[z, y]_{\beta} \gamma w, z\right]_{\delta} \alpha a=0} \\
& {\left[y \gamma[z, w]_{\beta}, z\right]_{\delta} \alpha a+\left[[z, y]_{\beta} \gamma w, z\right]_{\delta} \alpha a=0} \\
& y \gamma\left[[z, w]_{\beta}, z\right]_{\delta} \alpha a+\left([y, z]_{\beta} \gamma[z, w]_{\delta}\right) \alpha a+[z, y]_{\beta} \gamma[w, z]_{\delta} \alpha a+\left[[z, y]_{\beta}, z\right]_{\delta} \gamma w \alpha a=0 \\
& y \gamma\left[[z, w]_{\beta}, z\right]_{\delta} \alpha a+[z, y]_{\beta} \gamma[w, z]_{\delta} \alpha a+[z, y]_{\beta} \gamma[w, z]_{\delta} \alpha a+\left[[z, y]_{\beta}, z\right]_{\delta} \gamma w \alpha a=0
\end{aligned}
$$

for all $z, y \in M$ and $\alpha, \beta, \delta \in \Gamma$, then by using (9), we get

$$
\begin{equation*}
\left[[z, y]_{\beta}, z\right]_{\delta} \gamma w \alpha a+2[z, y]_{\beta} \gamma[w, z]_{\delta} \alpha a=0 \tag{10}
\end{equation*}
$$

for all $z, y, w \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. Replace $w$ by $s=\left[w_{1}, w_{2}\right]_{\beta}$ for all $w_{1}, w_{2} \in M$ in (10)

$$
\left[[z, y]_{\beta}, z\right]_{\delta} \gamma s \alpha a+2[z, y]_{\beta} \gamma[s, z]_{\delta} \alpha a=0
$$

for all $z, y, s \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. By using relation (7), we get

$$
\left[[z, y]_{\beta}, z\right]_{\delta} \gamma a \alpha\left[w_{1}, w_{2}\right]_{\beta}^{*}+2[z, y]_{\beta} \gamma[s, z]_{\delta} \alpha a=0
$$

for all $z, y, s \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. By using relation (9), we get

$$
2[z, y]_{\beta} \gamma[s, z]_{\delta} \alpha a=0
$$

for all $z, y, s \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. Since $M$ is 2-torsion free, we obtain

$$
\begin{equation*}
[z, y]_{\beta} \gamma[s, z]_{\delta} \alpha a=0 \tag{11}
\end{equation*}
$$

for all $z, y, s \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. Putting in relation(11) $y \gamma r$ for $y$, for all $y, r \in M$ and $\alpha \in \Gamma$

$$
\begin{aligned}
{[z, y \gamma r]_{\beta} \gamma[s, z]_{\delta} \alpha a } & =0 \\
\left(y \gamma[z, r]_{\beta}+[z, y]_{\beta} \gamma r\right) \gamma[s, z]_{\delta} \alpha a & =0 \\
y \gamma[z, r]_{\beta} \gamma[s, z]_{\delta} \alpha a+[z, y]_{\beta} \gamma r \gamma[s, z]_{\delta} \alpha a & =0
\end{aligned}
$$

for all $z, y, r \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. By using relation (11), we get

$$
\begin{equation*}
\left[\left[z_{1}, z_{2}\right]_{\alpha}, y\right]_{\beta} \gamma r \gamma\left[s,\left[z_{1}, z_{2}\right]_{\alpha}\right]_{\delta} \alpha a=0 \tag{12}
\end{equation*}
$$

for all $z_{1}, z_{2}, y, r, s \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. Linearization (12) on $z_{1}$ yields

$$
\begin{equation*}
\left[\left[b_{1}, z_{2}\right]_{\alpha}, y\right]_{\beta} \gamma r \gamma\left[s,\left[b_{2}, z_{2}\right]_{\alpha}\right]_{\delta} \alpha a=-\left[\left[b_{2}, z_{2}\right]_{\alpha}, y\right]_{\beta} \gamma r \gamma\left[s,\left[b_{1}, z_{2}\right]_{\alpha}\right]_{\delta} \alpha a \tag{13}
\end{equation*}
$$

for all $b_{1}, b_{2}, z_{2}, y, r, s \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. Then we have from (13) that

$$
\begin{array}{r}
{\left[\left[b_{1}, z_{2}\right]_{\alpha}, y\right]_{\beta} \gamma r \gamma\left[s,\left[b_{2}, z_{2}\right]_{\alpha}\right]_{\delta} \alpha a \gamma r \gamma\left[\left[b_{1}, z_{2}\right]_{\alpha}, y\right]_{\beta} \gamma r \gamma\left[s,\left[b_{2}, z_{2}\right]_{\alpha}\right]_{\delta} \alpha a=} \\
-\left[\left[b_{1}, z_{2}\right]_{\alpha}, y\right]_{\beta} \gamma\left(r \gamma\left[s,\left[b_{2}, z_{2}\right]_{\alpha}\right]_{\delta} \alpha a \gamma r \gamma\left[\left[b_{2}, z_{2}\right]_{\alpha}, y\right]_{\delta} \gamma r\right) \gamma\left[s,\left[b_{1}, z_{2}\right]_{\alpha}\right]_{\beta} \alpha a=0 \tag{14}
\end{array}
$$

for all $b_{1}, b_{2}, z_{2}, y, r, s \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. Then by using (12), we obtain

$$
\left[\left[b_{1}, z_{2}\right]_{\alpha}, y\right]_{\beta} \gamma r \gamma\left[s,\left[b_{2}, z_{2}\right]_{\alpha}\right]_{\delta} \alpha a \gamma r \gamma\left[\left[b_{1}, z_{2}\right]_{\alpha}, y\right]_{\beta} \gamma r \gamma\left[s,\left[b_{2}, z_{2}\right]_{\alpha}\right]_{\delta} \alpha a=0
$$

for all $b_{1}, b_{2}, z_{2}, y, r, s \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. Since $M$ is a prime ring, we get

$$
\begin{equation*}
\left[\left[b_{1}, z_{2}\right]_{\alpha}, y\right]_{\beta} \gamma r \gamma\left[s,\left[b_{2}, z_{2}\right]_{\alpha}\right]_{\delta} \alpha a=0 \tag{15}
\end{equation*}
$$

for all $b_{1}, b_{2}, z_{2}, y, r, s \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. Now replace $z_{2}$ by $x_{1}+x_{2}$ in (15) for all $x_{1}, x_{2} \in M$, we get ( see how (15) was obtained from (12))

$$
\begin{equation*}
\left[\left[b_{1}, x_{1}\right]_{\alpha}, y\right]_{\beta} \gamma r \gamma\left[s,\left[b_{2}, x_{2}\right]_{\alpha}\right]_{\delta} \alpha a=0 \tag{16}
\end{equation*}
$$

for all $b_{1}, b_{2}, x_{1}, x_{2}, y, r, s \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. Putting $u=\left[b_{1}, x_{1}\right]_{\alpha}$ and $q=\left[b_{2}, x_{2}\right]_{\alpha}$, the relation (16) leads to

$$
\begin{equation*}
[u, y]_{\beta} \gamma r \gamma[s, q]_{\delta} \alpha a=0 \tag{17}
\end{equation*}
$$

for all $u, y, s, r, q \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. Since $M$ is a non-commutative prime $\Gamma$-ring with involution, then by using Lemma 2.2, we get

$$
\begin{equation*}
\left[\left[w_{1}, w_{2}\right]_{\beta}, q\right]_{\delta} \alpha a=0 \tag{18}
\end{equation*}
$$

for all $w_{1}, w_{2}, q \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. The substitution $w_{1} \gamma w_{2}^{*}$ for $w_{2}$ in (18)

$$
\begin{aligned}
& {\left[\left[w_{1}, w_{1} \gamma w_{2}^{*}\right]_{\alpha}, q\right]_{\delta} \alpha a=0} \\
& {\left[w_{1} \gamma\left[w_{1}, w_{2}^{*}\right]_{\alpha}+\left[w_{1}, w_{1}\right]_{\alpha} \gamma w_{2}^{*}, q\right]_{\delta} \alpha a=0} \\
& {\left[w_{1} \gamma\left[w_{1}, w_{2}^{*}\right]_{\alpha}, q\right]_{\delta} \alpha a=0} \\
& w_{1} \gamma\left[\left[w_{1}, w_{2}^{*}\right]_{\alpha}, q\right]_{\delta} \alpha a+\left[w_{1}, q\right]_{\delta} \gamma\left[w_{1}, w_{2}^{*}\right]_{\alpha} \alpha a=0
\end{aligned}
$$

for all $w_{1}, w_{2}^{*}, q, a \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. By using relation (18) and assumption (A), we obtain

$$
\left[w_{1}, q\right]_{\delta} \gamma\left[w_{1}, w_{2}^{*}\right]_{\alpha} \alpha a=0
$$

for all $w_{1}, w_{2}^{*}, q, a \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. By using relation (7) we get

$$
\begin{equation*}
\left[w_{1}, q\right]_{\beta} \gamma a \gamma\left[w_{2}, w_{1}^{*}\right]_{\delta}=0 \tag{19}
\end{equation*}
$$

for all $w_{1}, w_{2}, q \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. Replace $w_{2}$ by $r \alpha w_{2}$ in (19)

$$
\begin{aligned}
& {\left[w_{1}, q\right]_{\beta} \gamma a \gamma\left[r \alpha w_{2}, w_{1}^{*}\right]_{\delta}=0} \\
& {\left[w_{1}, q\right]_{\beta} \gamma a \gamma\left(r \alpha\left[w_{2}, w_{1}^{*}\right]_{\delta}+\left[r, w_{1}^{*}\right]_{\delta} \alpha w_{2}\right)=0} \\
& {\left[w_{1}, q\right]_{\beta} \gamma a \gamma r \alpha\left[w_{2}, w_{1}^{*}\right]_{\delta}+\left[w_{1}, q\right]_{\beta} \gamma a \gamma\left[r, w_{1}^{*}\right]_{\delta} \alpha w_{2}=0}
\end{aligned}
$$

for all $w_{1}, r, q, a \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. Then by using (19) we get

$$
\begin{equation*}
\left[w_{1}, q\right]_{\beta} \gamma a \alpha r \gamma\left[w_{2}, w_{1}^{*}\right]_{\delta}=0 \tag{20}
\end{equation*}
$$

for all $w_{1}, w_{2}, q, r \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. From the relation (20) one obtains ( see how (15) was obtained from its previous relation)

$$
\begin{equation*}
\left[w_{1}, q\right]_{\beta} \gamma a \alpha r \gamma\left[w_{2}, t\right]_{\delta}=0 \tag{21}
\end{equation*}
$$

for all $w_{1}, w_{2}, q, r, t \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. Since $M$ is non-commutative prime $\Gamma$-ring with involution, we get

$$
\begin{equation*}
\left[w_{1}, q\right]_{\beta} \gamma a=0 \tag{22}
\end{equation*}
$$

for all $w_{1}, q \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. Replace $w_{1}$ by $w_{1} \alpha r$ in (22)

$$
\left[w_{1} \gamma r, q\right]_{\delta} \gamma a=w_{1} \gamma[r, q]_{\beta} \gamma a+\left[w_{1}, q\right]_{\delta} \gamma r \gamma a=0
$$

for all $w_{1}, q, r \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. Then by using relation (22) we obtain

$$
\begin{equation*}
\left[w_{1}, q\right]_{\beta} \alpha r \gamma a=0 \tag{23}
\end{equation*}
$$

for all $w_{1}, q, r \in M$ and $\alpha, \beta, \delta, \gamma \in \Gamma$. Since $M$ is a non-commutative prime $\Gamma$-ring with involution, then from relation (23) we get $a=0$.

Lemma 2.4. If $M$ is a completely prime $\Gamma$-ring with 2 -torsion free satisfying assumption (A), then every Jordan derivation on $M$ is a derivation on $M$.

Proof. By using [1], we have

$$
\begin{equation*}
d(x \alpha y)=x \alpha d(y)+y \alpha d(x) \tag{24}
\end{equation*}
$$

for all $x, y \in M$ and $\alpha \in \Gamma$. By using [2], we have

$$
\begin{equation*}
d(x \alpha y)=d(x) \alpha y+d(y) \alpha x \tag{25}
\end{equation*}
$$

for all $x, y \in M$ and $\alpha \in \Gamma$. If we combine the relation (24) and (25), then we get

$$
\begin{equation*}
d(x \alpha y)=d(x) \alpha y+x \alpha d(y) \tag{26}
\end{equation*}
$$

Lemma 2.5. Let $M$ be a 2-torsion free prime $\Gamma$-ring with involution satisfying assumption (A) and let $d: M \rightarrow M$ be a non-zero Jordan $\Gamma^{*}$-derivation, then $M$ is commutative if and only if $d$ is a $\Gamma^{*}$-derivation.

Proof. Let M be a commutative $\Gamma$-ring with involution, since $d$ is a non-zero Jordan $\Gamma^{*}$-derivation we have

$$
\begin{equation*}
d(x \alpha x)=d(x) \alpha x^{*}+x \alpha d(x) \tag{27}
\end{equation*}
$$

for all $x \in M$ and $\alpha \in \Gamma$. Linearization of (27) yields

$$
\begin{equation*}
d(x \alpha y+y \alpha x)=d(x) \alpha y^{*}+x \alpha d(y)+d(y) \alpha x^{*}+y \alpha d(x) \tag{28}
\end{equation*}
$$

for all $x, y \in M$ and $\alpha \in \Gamma$. Replace $y$ by $x \delta y+y \beta x$ in (28) and since $M$ is 2 -torsion free we get

$$
\begin{equation*}
d(x \alpha y \beta x)=d(x) \alpha y^{*} \beta x^{*}+\operatorname{x\alpha d}(y) \beta x^{*}+x \alpha y \beta d(x) \tag{29}
\end{equation*}
$$

for all $x, y \in M$ and $\alpha, \beta \in \Gamma$. Putting $x+z$ for $x$ in (29) we obtain

$$
\begin{align*}
& d(x \alpha y \beta z+z \alpha y \beta x)=d(x) \alpha y^{*} \beta z^{*}+x \alpha d(y) \beta z^{*}+x \alpha y \beta d(z)+ \\
& d(z) \alpha y^{*} \beta x^{*}+z \alpha d(y) \beta x^{*}+z \alpha y \beta d(x) \tag{30}
\end{align*}
$$

for all $x, y, z \in M$ and $\alpha, \beta \in \Gamma$. Replace $x$ by $x \delta y$ and $y$ by $z$ in relation (28) we get

$$
\begin{align*}
& d(x \delta y \alpha z+z \alpha x \delta y)=d(x) \alpha y^{*} \beta z^{*}+x \alpha d(y) \beta z^{*}+d(z) \alpha y^{*} \delta x^{*}+x \alpha y \beta d(z)+ \\
& +z \alpha d(x) \beta y^{*}+z \alpha x \beta d(y) \tag{31}
\end{align*}
$$

for all $x, y, z \in M$ and $\alpha, \beta, \delta \in \Gamma$. Since $M$ is commutative, comparing the relation (30) and (31) we get

$$
\begin{equation*}
B(x, y) \alpha z^{*}+z \alpha B(y, x)=0 \tag{32}
\end{equation*}
$$

for all $x, y, z \in M$ and $\alpha, \beta \in \Gamma$, where $B(x, y)$ stands for $d(x \alpha y)-d(x) \alpha y^{*}-x \alpha d(y)$, since $B(x, y)=-B(y, x)$, then from the relation (32) we obtain

$$
\begin{equation*}
B(x, y) \alpha\left(z^{*}-z\right)=0 \tag{33}
\end{equation*}
$$

for all $x, y, z \in M$ and $\alpha \in \Gamma$. Right multiplication the relation (33) by $r$ we get

$$
\begin{equation*}
B(x, y) \alpha r \beta\left(z^{*}-z\right)=0 \tag{34}
\end{equation*}
$$

for all $x, y, z \in M$ and $\alpha, \beta \in \Gamma$. Since $M$ is prime, then either $d$ is a $\Gamma^{*}$-derivation, or $z=z^{*}$ for all $z \in M$. If $z=z^{*}$ for all $z \in M$, then from the relation (27) we obtain

$$
\begin{equation*}
d(x \alpha x)=d(x) \alpha x+x \alpha d(x) \tag{35}
\end{equation*}
$$

for all $x \in M$ and $\alpha \in \Gamma$. Now by using Lemma( 2.4) we get

$$
\begin{equation*}
d(x \alpha y)=d(x) \alpha y+x \alpha d(y) \tag{36}
\end{equation*}
$$

for all $x, y \in M$ and $\alpha \in \Gamma$. Then by using the above relation and since $y=y^{*}$ for all $y \in M$, we conclude that $d$ is a $\Gamma^{*}$-derivation. To prove the converse, assume $d$ is a non-zero $\Gamma^{*}$-derivation, then by using Lemma 2.1 we get $M$ is a commutative $\Gamma^{*}$-ring.

Theorem 2.6. Let $M$ be a 2-torsion free prime $\Gamma$-ring with involution satisfies assumption ( $A$ ) and let $d: M \rightarrow M$ be a non-zero Jordan $\Gamma^{*}$-derivation such that $d\left([x, y]_{\alpha}\right)=$ 0 for all $x, y \in M$ and $\alpha \in \Gamma$, then $M$ is a commutative $\Gamma^{*}$-ring.

Proof. We have

$$
\begin{equation*}
d(x \alpha y)=d(y \alpha x) \tag{37}
\end{equation*}
$$

for all $x, y \in M$ and $\alpha \in \Gamma$. Replace $y$ by $y \beta z+z \beta y$ in (37) we obtain

$$
\begin{equation*}
d(x \alpha y \beta z+z \beta y \alpha x)=d(y \beta z \alpha x+x \alpha z \beta y) \tag{38}
\end{equation*}
$$

for all $x, y, z \in M$ and $\alpha, \beta \in \Gamma$. Using relation (30) we obtain

$$
\begin{align*}
& d(x \alpha y \beta z+z \beta y \alpha x)=d(x) \alpha y^{*} \beta z^{*}+x \alpha d(y) \beta z^{*}+x \alpha y \beta d(z)+ \\
& d(z) \beta y^{*} \alpha x^{*}+z \beta d(y) \alpha x^{*}+z \beta y \alpha d(x) \tag{39}
\end{align*}
$$

for all $x, y, z \in M$ and $\alpha, \beta \in \Gamma$ and

$$
\begin{align*}
& d(y \beta z \alpha x+x \alpha z \beta y)=d(y) \beta z^{*} \alpha x^{*}+y \beta d(z) \alpha x^{*}+y \beta z \alpha d(x)+ \\
& d(x) \alpha z^{*} \beta y^{*}+x \alpha d(z) \beta y^{*}+x \alpha z \beta d(y) \tag{40}
\end{align*}
$$

for all $x, y, z \in M$ and $\alpha, \beta \in \Gamma$. According to (39), (40) and (38) we get

$$
\begin{align*}
& d(x) \alpha\left[y^{*}, z^{*}\right]_{\beta}+[z, y]_{\beta} \alpha d(x)+x \alpha\left(d(y) \beta z^{*}+y \beta d(z)-d(z) \beta y^{*}-z \beta d(y)\right) \\
& -\left(d(y) \beta z^{*}+y \beta d(z)-d(z) \beta y^{*}-z \beta d(y)\right) \alpha x^{*}=0 \tag{41}
\end{align*}
$$

for all $x, y, z \in M$ and $\alpha, \beta \in \Gamma$. Putting in (41) $[a, b]_{\alpha}$ for $x$, we obtain

$$
\begin{equation*}
A(y, z) \gamma[a, b]_{\alpha}^{*}=[a, b]_{\alpha} \gamma A(y, z) \tag{42}
\end{equation*}
$$

for all $y, z \in M$ and $\alpha, \beta \in \Gamma$, where $A(y, z)$ stand by $d(y) \beta z^{*}+y \beta d(z)-d(z) \beta y^{*}-z \beta d(y)$. Now if $M$ is a non-commutative prime $\Gamma$-ring with involution, then by using Lemma 2.3 we get from (42)

$$
\begin{equation*}
A(y, z)=0 \tag{43}
\end{equation*}
$$

for all $x, y, z \in M$ and $\alpha, \beta \in \Gamma$. Using relations (37) and (28) we get

$$
\begin{equation*}
2 d(y \beta z)=d(y) \beta z^{*}+y \beta d(z)+d(z) \beta y^{*}+z \beta d(y) \tag{44}
\end{equation*}
$$

for all $y, z \in M$ and $\beta \in \Gamma$. Since $M$ is a 2 -torsion free, then using (43) and (44) we conclude that $d$ is a $\Gamma^{*}$-derivation, then by using Lemma 2.1 we get $d=0$, which is a contradiction. Then the proof is complete.

Corollary 2.7. Let $M$ be a 2-torsion free prime $\Gamma$-ring with involution and let $d$ : $M \rightarrow M$ be a non-zero Jordan $\Gamma^{*}$-derivation such that $d\left([x, y]_{\alpha}\right)=0$ for all $x, y \in M$ and $\alpha \in \Gamma$, then $d$ is a $\Gamma^{*}$-derivation.

Proof. By using Theorem 2.6 we get $M$ is commutative prime $\Gamma$-ring with involution, also by using Lemma 2.5 we get $d$ is $\Gamma^{*}$-derivation.

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